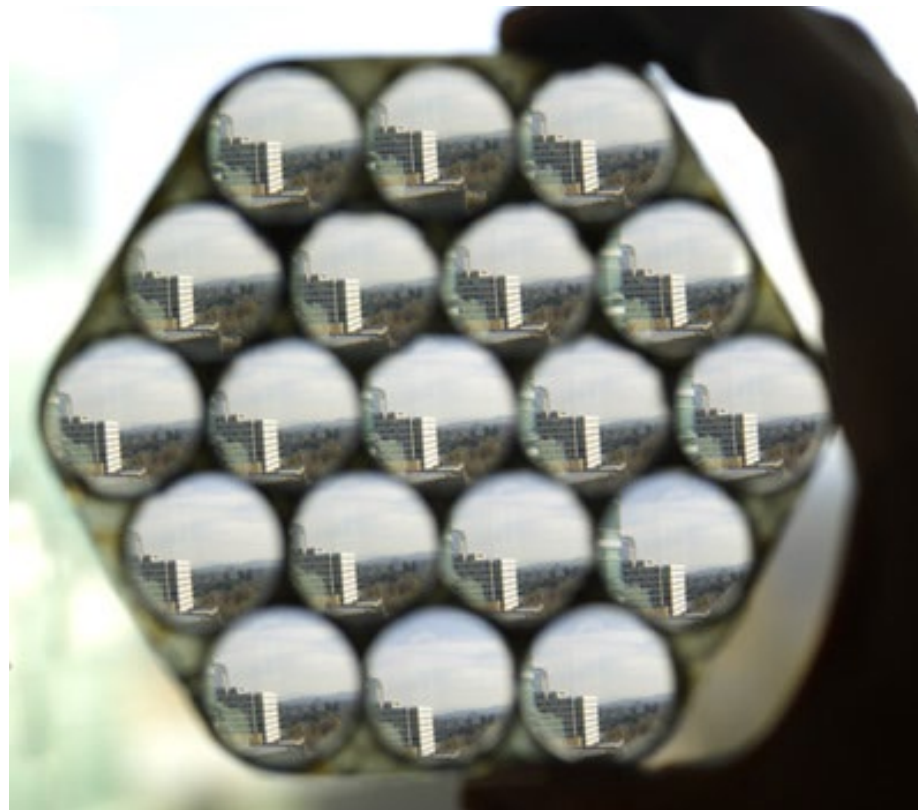


Introduction



Lecture etiquette

- Lecture slides (PDF) are posted on the course website before each lecture.
- You are expected to attend lectures in person.
- Feel free to ask questions! Please make sure to raise your hand to both ask your own questions and answer mine.

Overview of today's lecture

- Teaching staff introductions
- What is computational photography?
- Course fast-forward and logistics

Teaching staff introductions

Instructor: Ioannis (Yannis) Gkioulekas (he/him)

You can call me Yannis.



Originally from Greece



National Technical University of Athens (2004-09)



Harvard University (2009-17)



Carnegie Mellon University (2017-now)

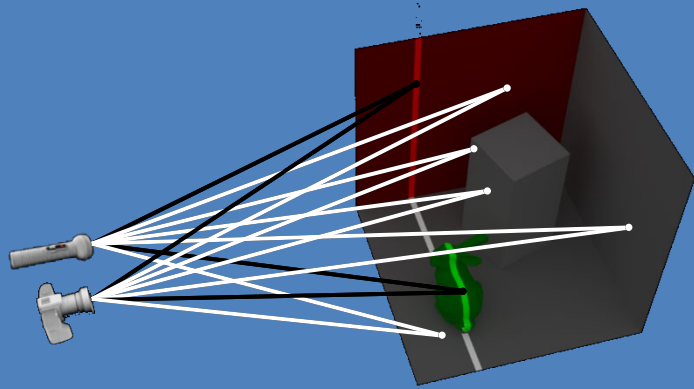


Yannis at Harvard in 2011

My website: <http://www.cs.cmu.edu/~igkioule>

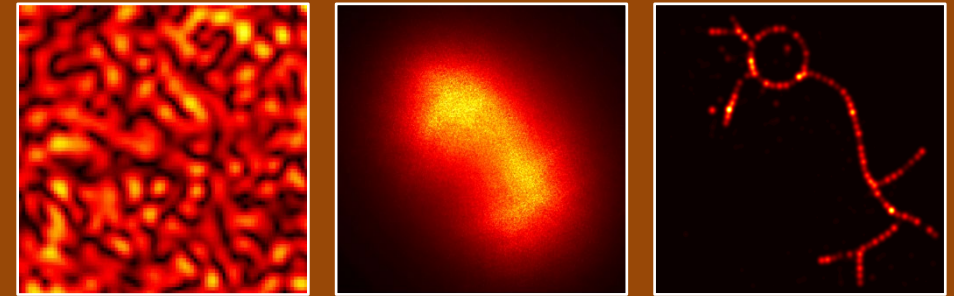
See also: <http://imaging.cs.cmu.edu/>

3D sensing



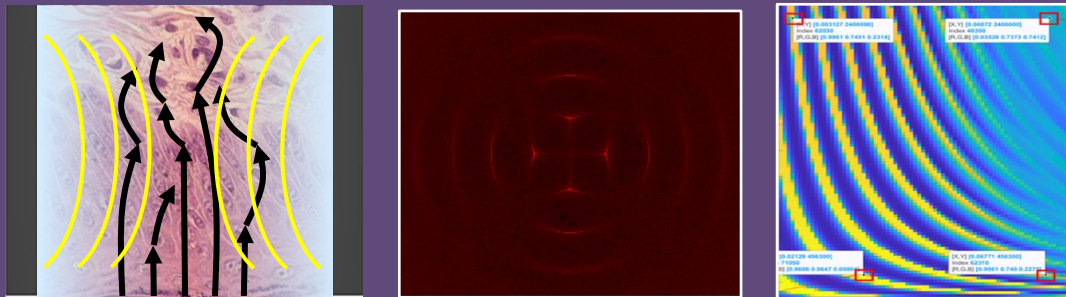
- micrometer 3D sensing using interferometry
- ultrafast 3D sensing using ultrasonic lenses

speckle imaging



- Monte Carlo rendering of wave optics
- fluorescence microscopy

acousto-optics



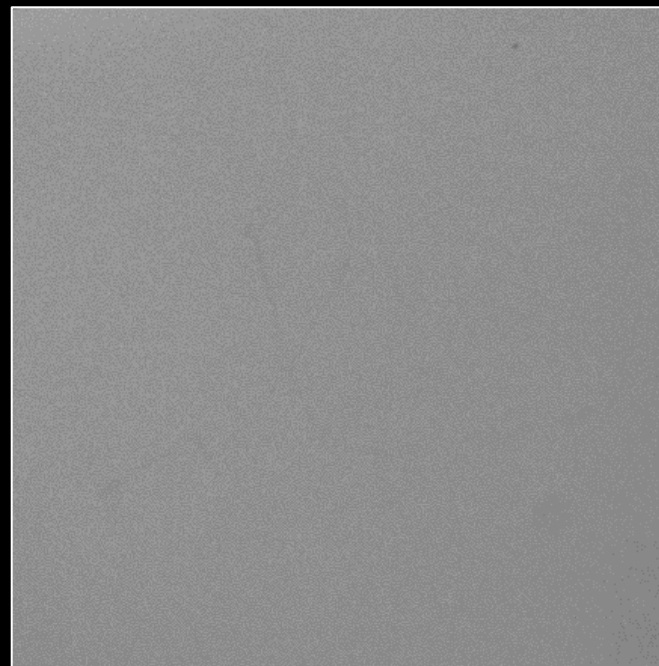
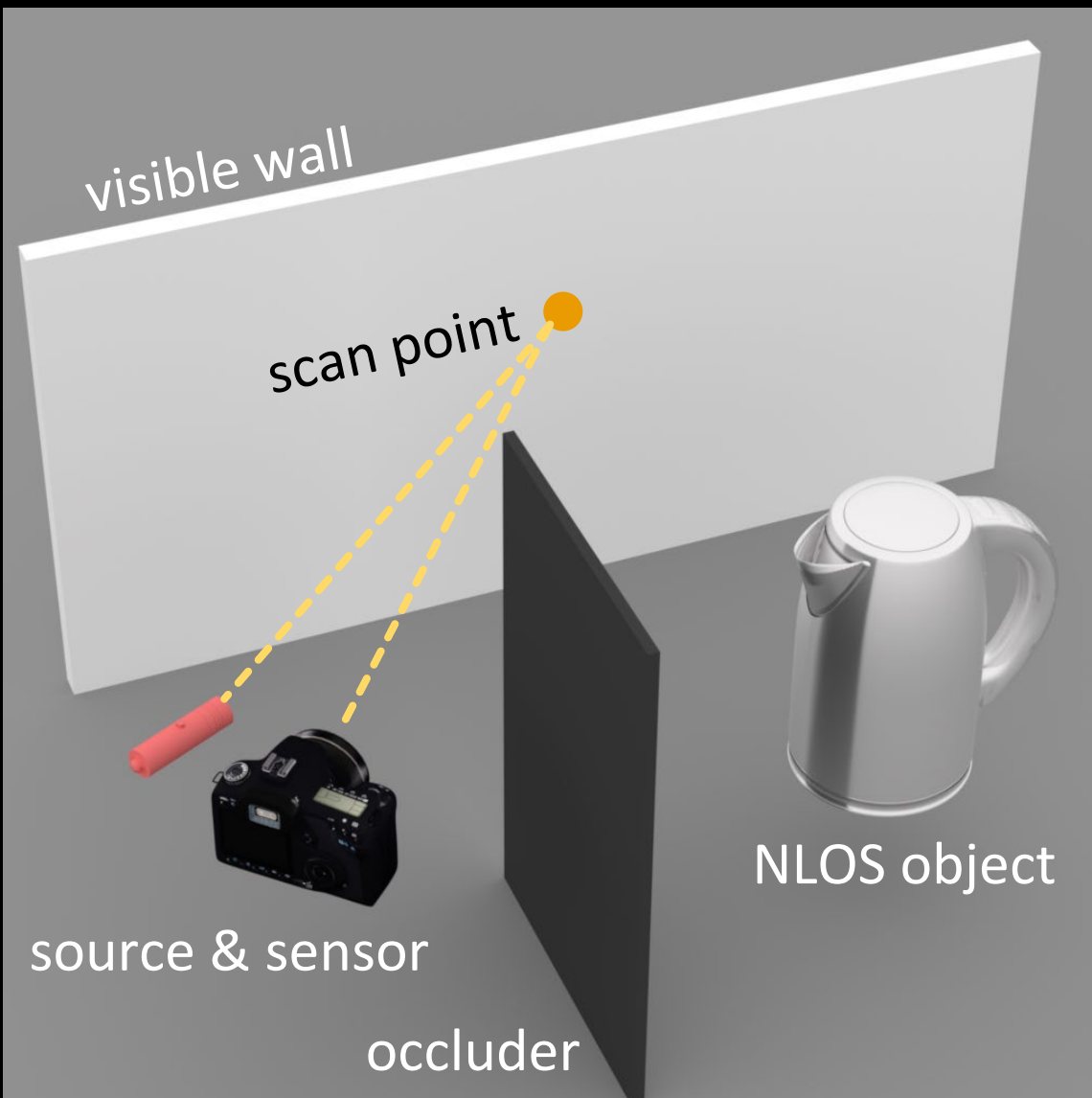
- rendering refractive radiative transfer
- steering light inside tissue

tissue imaging



- differentiable rendering for tissue tomography
- blood and vein imaging

Looking around corners

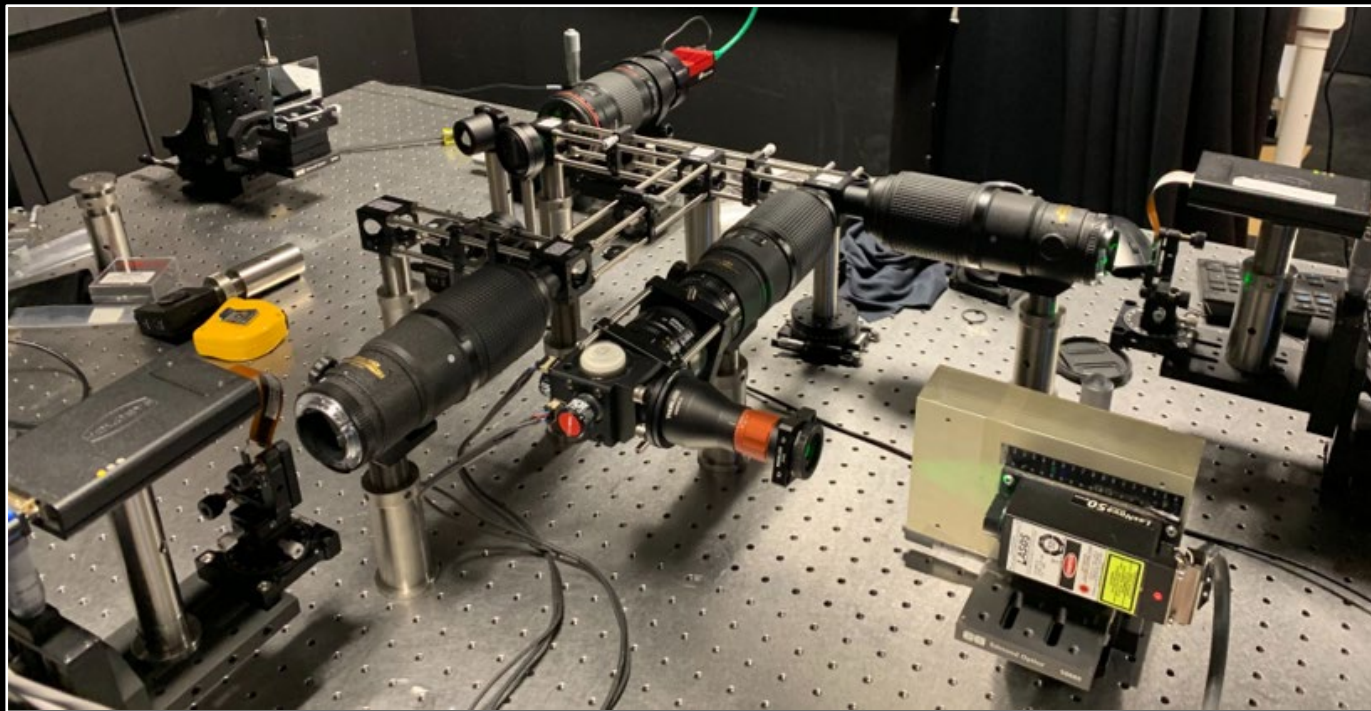


what a regular
camera sees

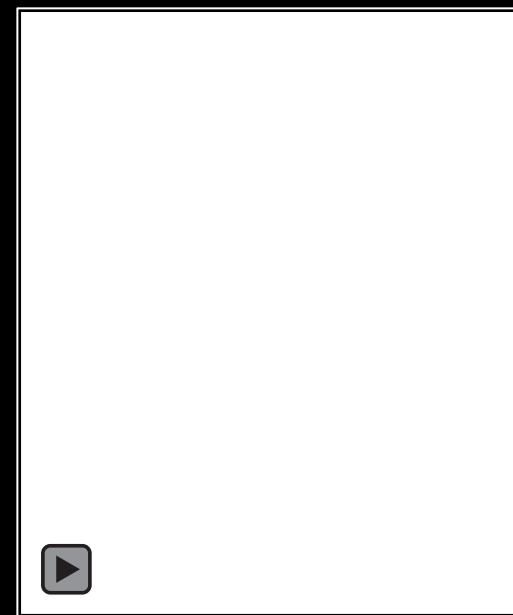


what we can
reconstruct

Seeing light in flight

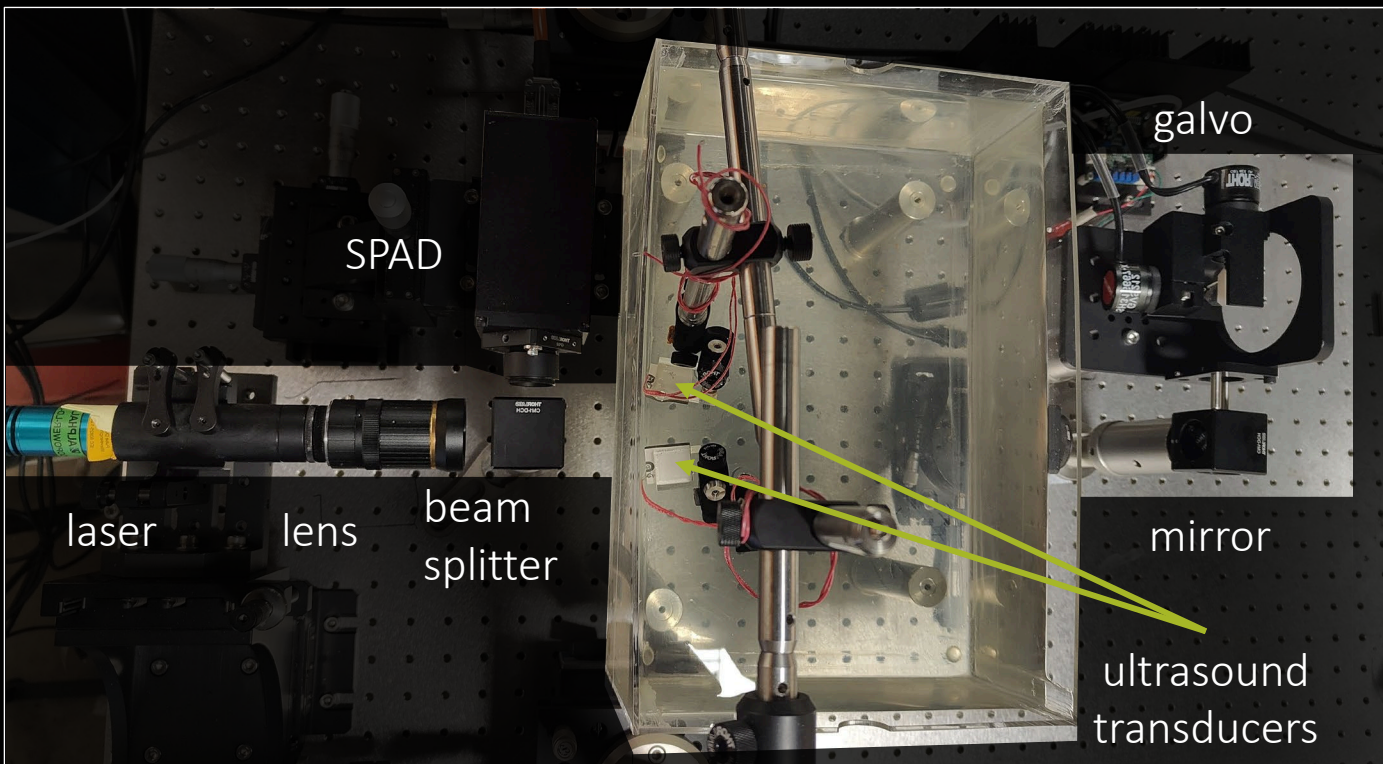


camera for capturing video at 10^{15} frames per second

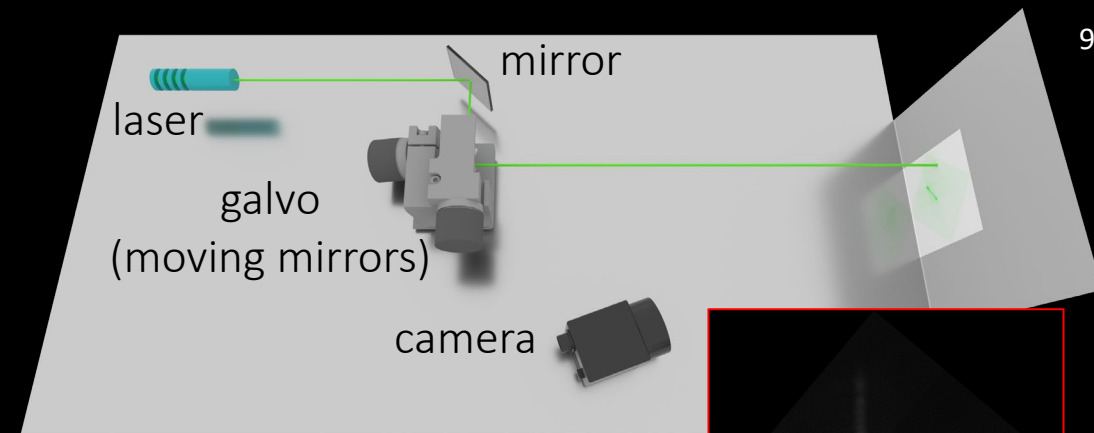


Ultrafast lidar

9

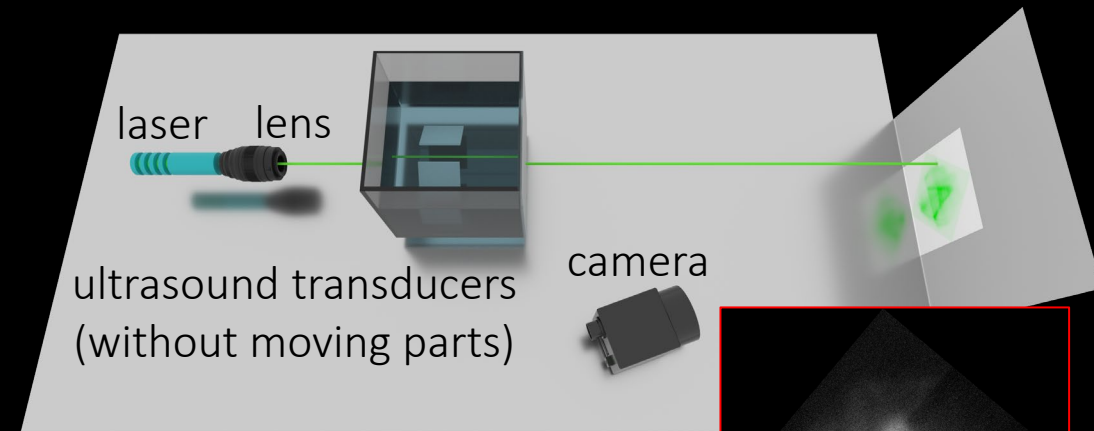
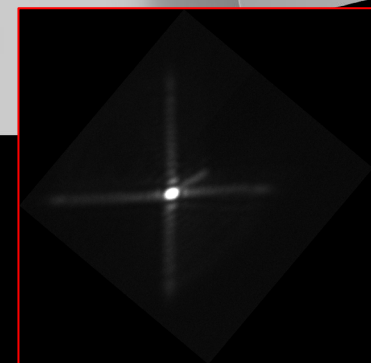


1000 × faster than a
commercial Velodyne lidar



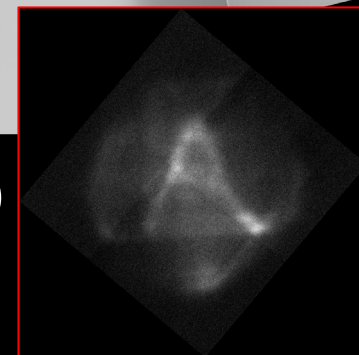
galvo steering (1 kHz)

1 ms exposure



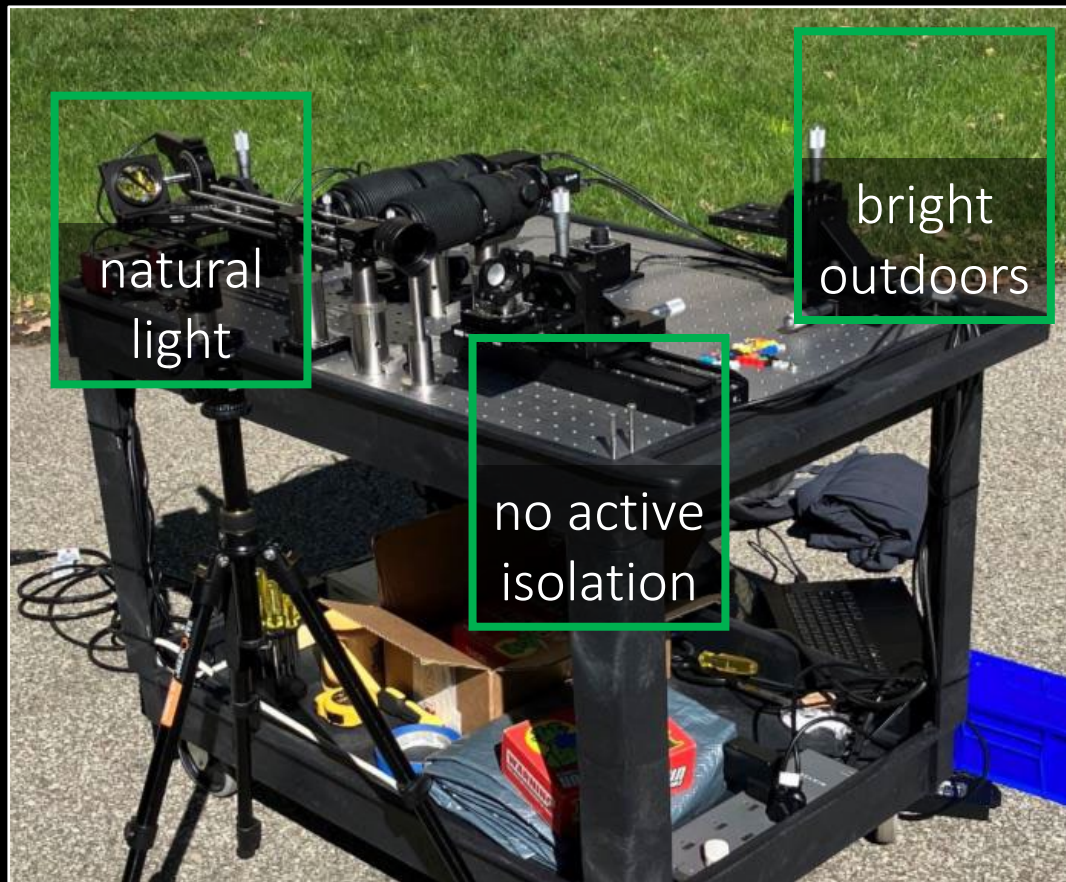
our acousto-optic steering (1 MHz)

1 ms exposure



<http://imaging.cs.cmu.edu/>

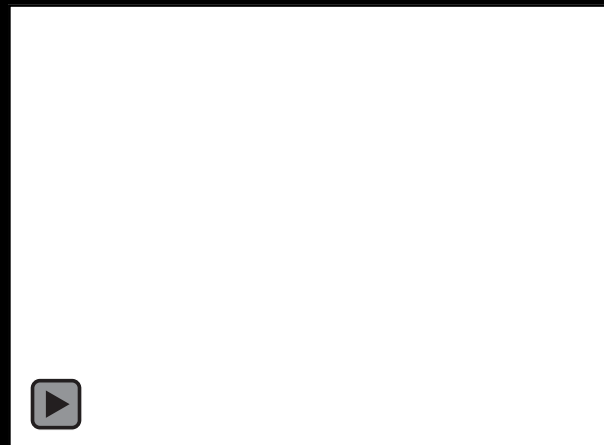
Sunlight micro-3D scanning



scene



depth map



input images

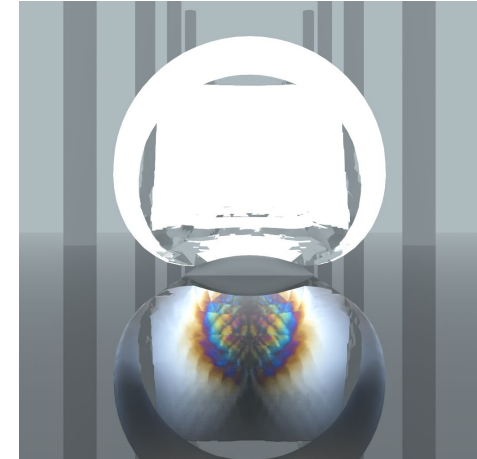
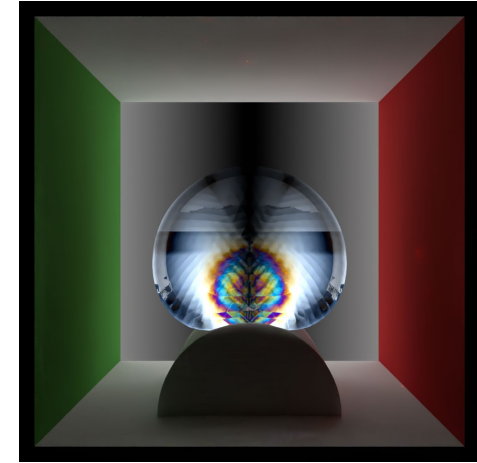


scene transient

TA: Petra Schlenker (she/they)

Master's student in computer science

Hobbies: Crochet, singing, playing piano,
photography



TA: Shengxi Wu (she/her)

MSR student, advised by Matthew O'Toole

Current Interest: Computational Imaging

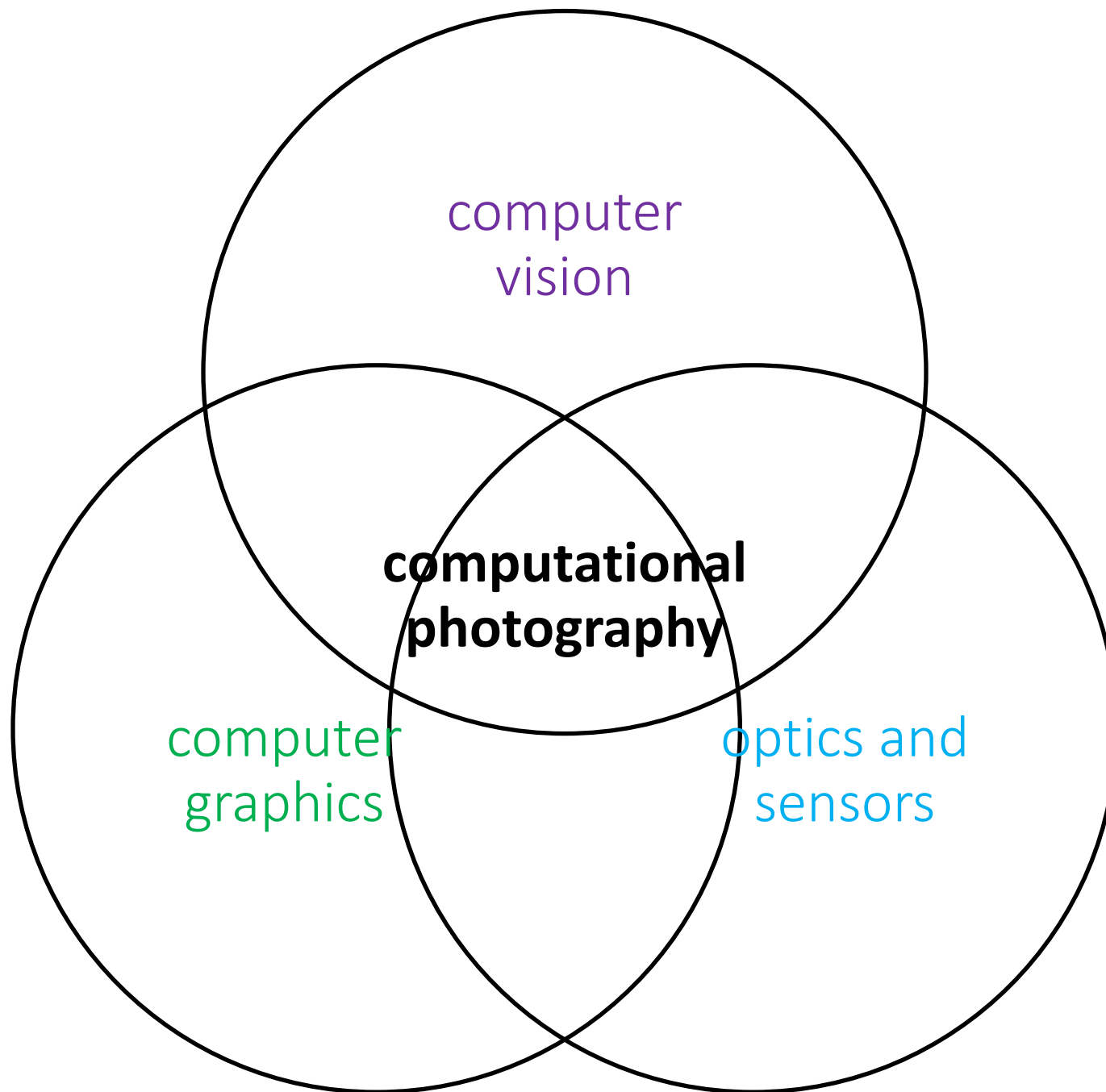
Contact me: shengxiw@andrew.cmu.edu



Optical vibration sensing & more



What is computational photography?



Analog photography



optics to focus light on
an image plane



film to capture focused light
(chemical process)

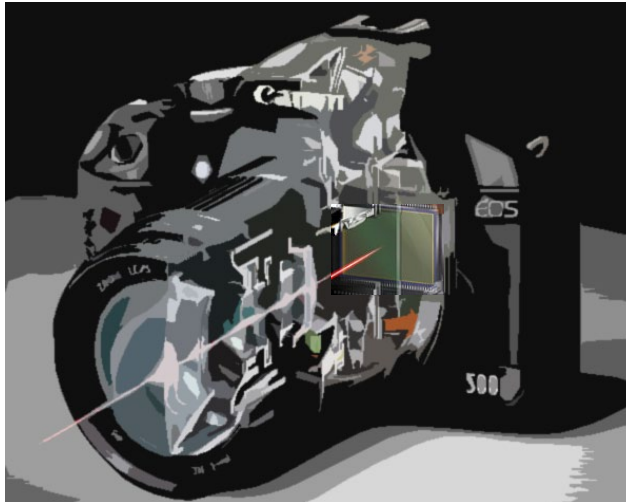


dark room for limited post-
processing (chemical process)

Digital photography



optics to focus light on
an image plane



digital sensor to capture focused
light (electrical process)

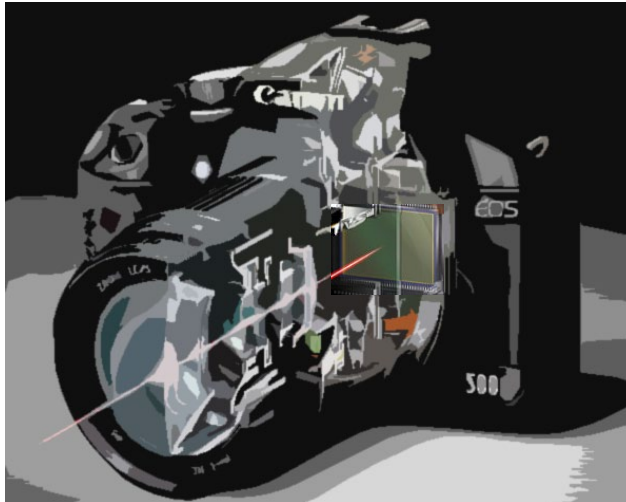


on-board processor for post-
processing (digital process)

Computational photography



optics to focus light on
an image plane



digital sensor to capture focused
light (electrical process)



arbitrary computation
between sensor and image

Overcome limitations of digital photography

Image enhancement and photographic look



camera output



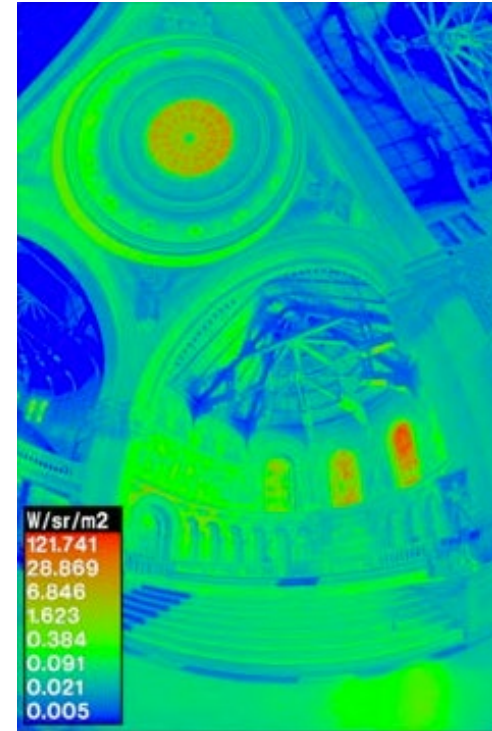
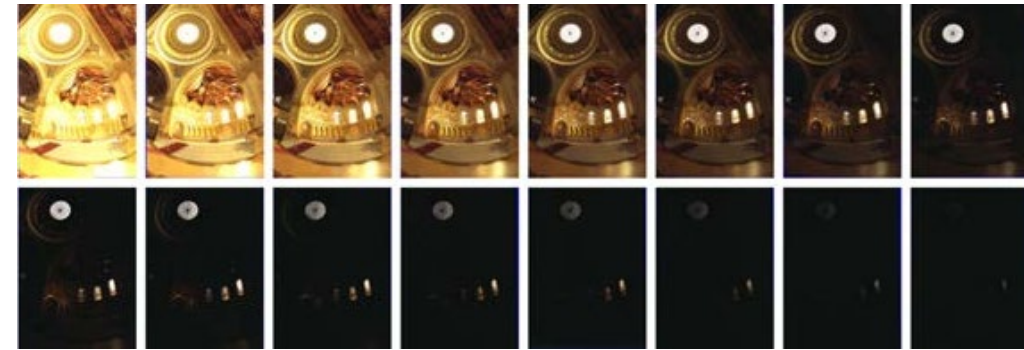
image after stylistic tonemapping

Overcome limitations of digital photography

High dynamic range (HDR) imaging



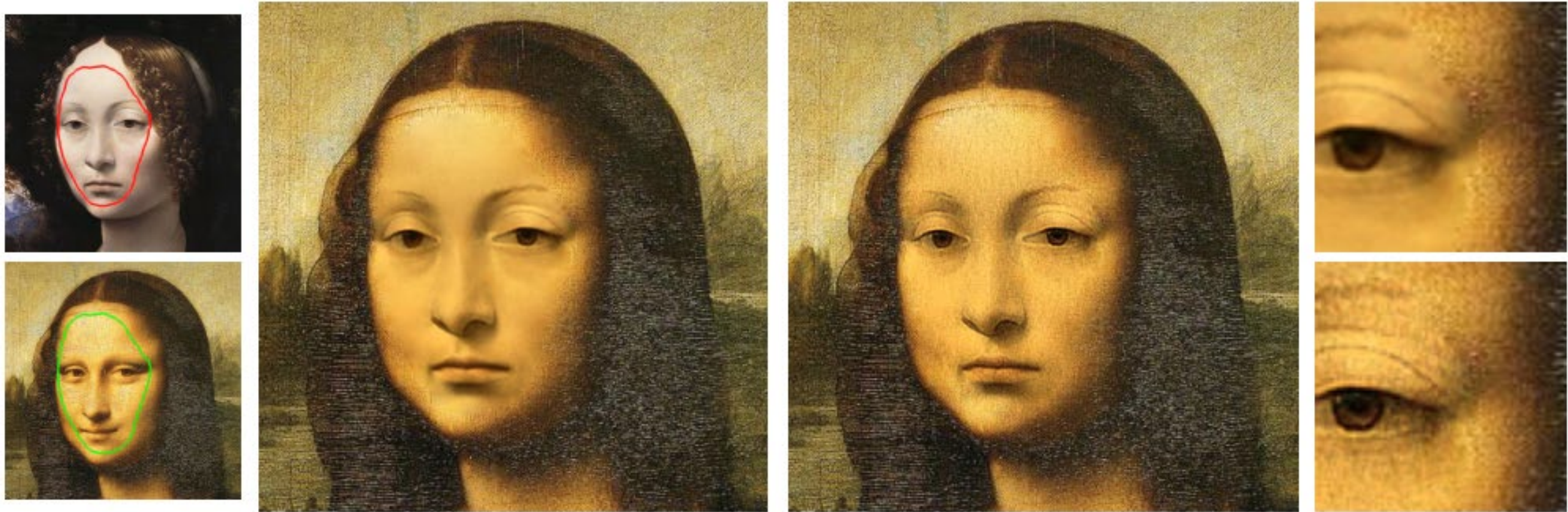
One of your
homeworks!



[example from www.dpreview.com] [Debevec and Malik, SIGGRAPH 1997]

Create realistic new imagery

Image blending and harmonization



One of your
homeworks!

Post-capture image compositing

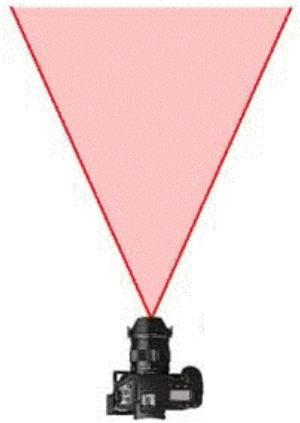
Computational zoom



images captured at three zoom settings

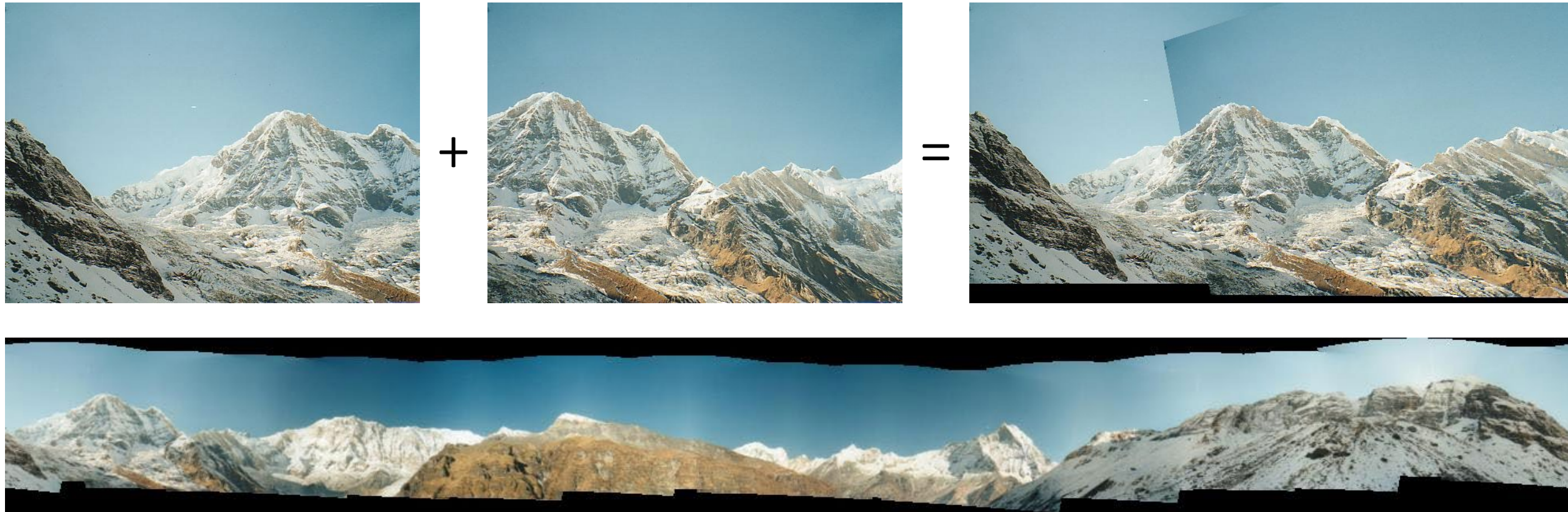


post-capture synthesis of new zoom views



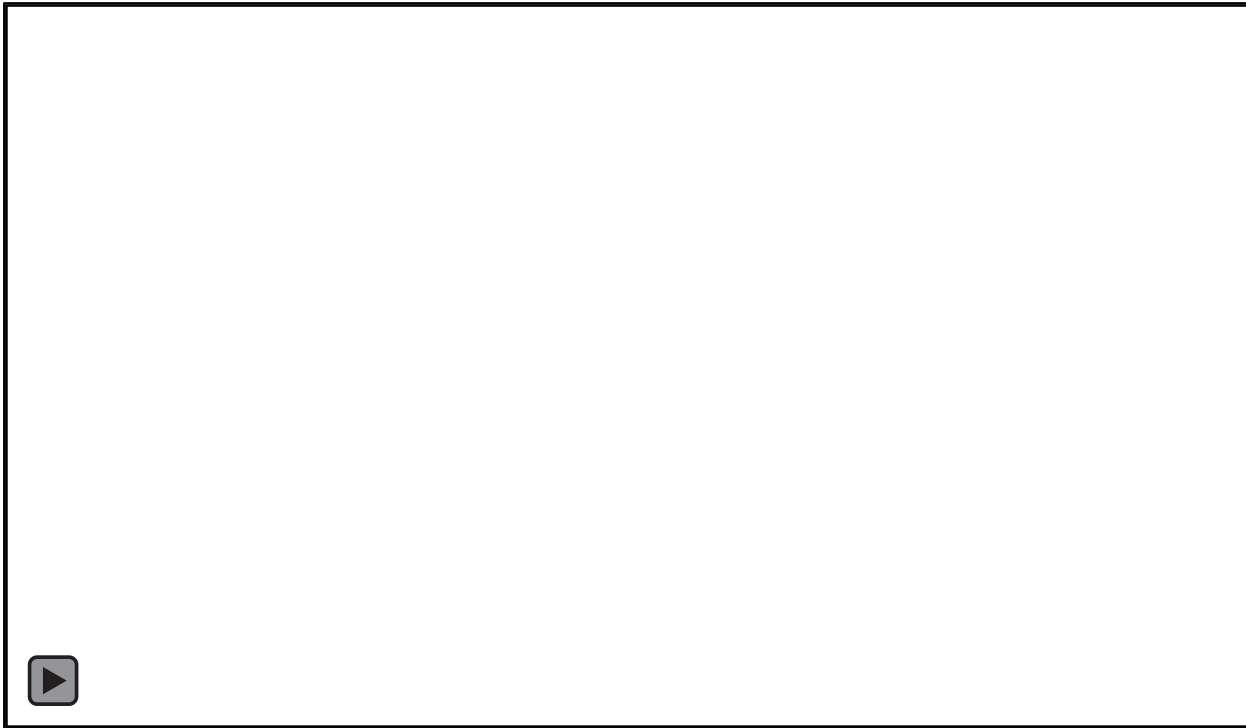
Process image collections

Auto-stitching images into panoramas

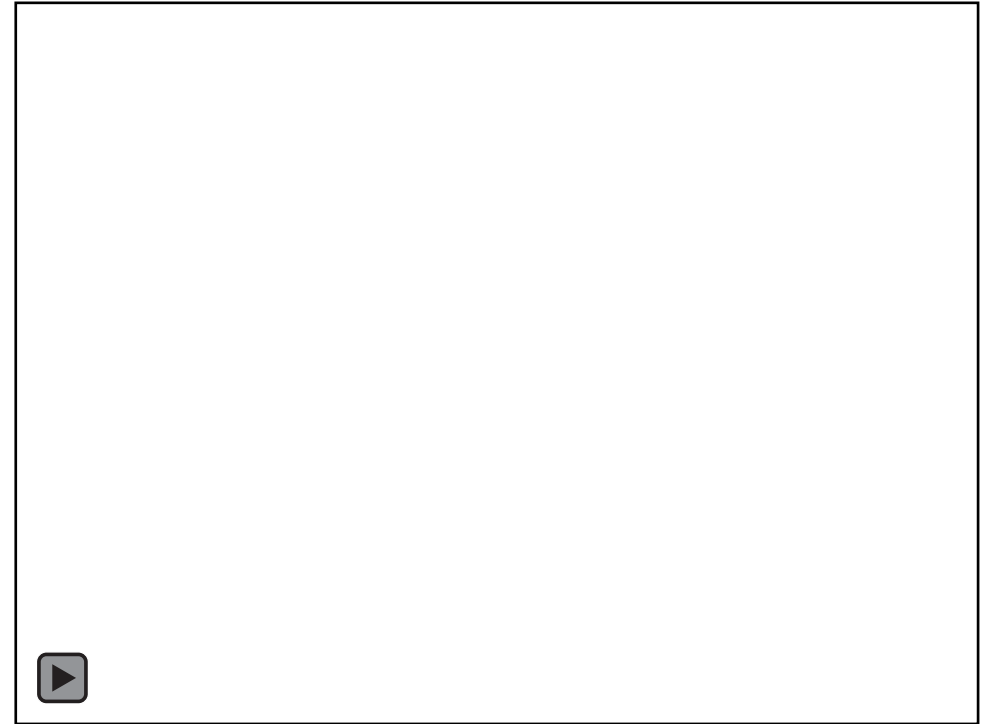


Process (very) large image collections

Using the Internet as your camera



reconstructing cities from Internet photos

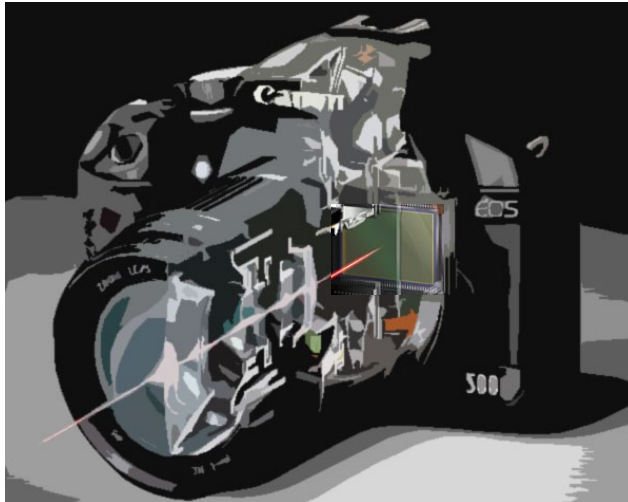


time-lapse from Internet photos

Computational photography



optics to focus light on
an image plane



digital sensor to capture focused
light (electrical process)

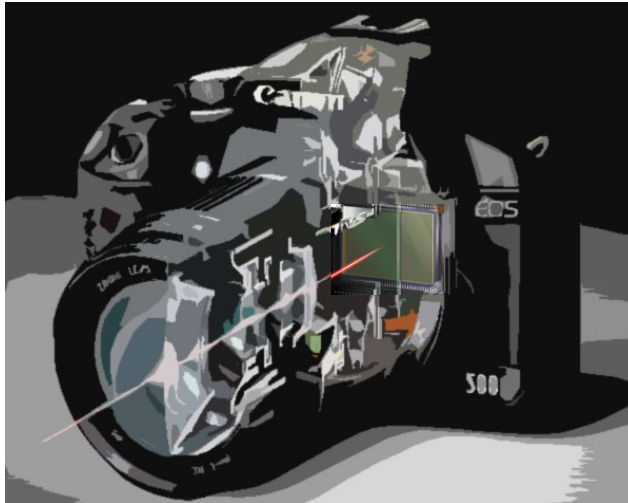


arbitrary computation
between sensor and image

Computational photography



generalized optics
between scene and sensor



digital sensor to capture focused
light (electrical process)



arbitrary computation
between sensor and image

*Sometimes people differentiate between *computational photography* and *computational imaging*. We use them interchangeably.

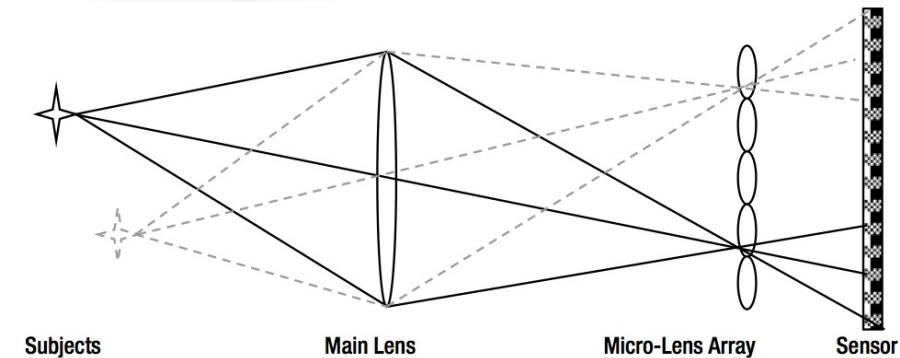
Capture more than 2D images

Lightfield cameras for plenoptic imaging



post-capture refocusing

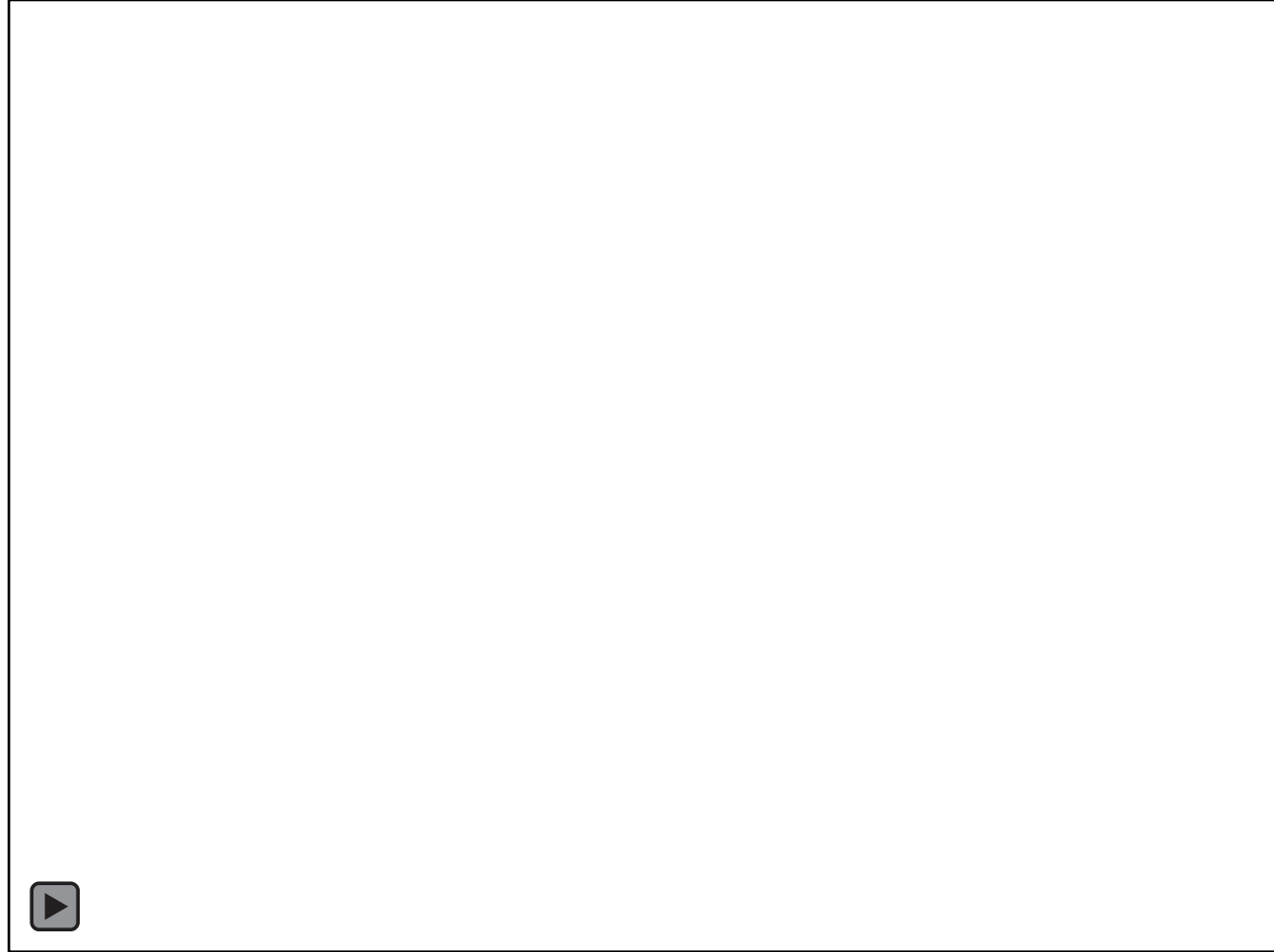
One of your
homeworks!



[Ng et al., SIGGRAPH 2005] [Lytro Inc.]

Capture more than 2D images

Lightfield cameras for plenoptic imaging



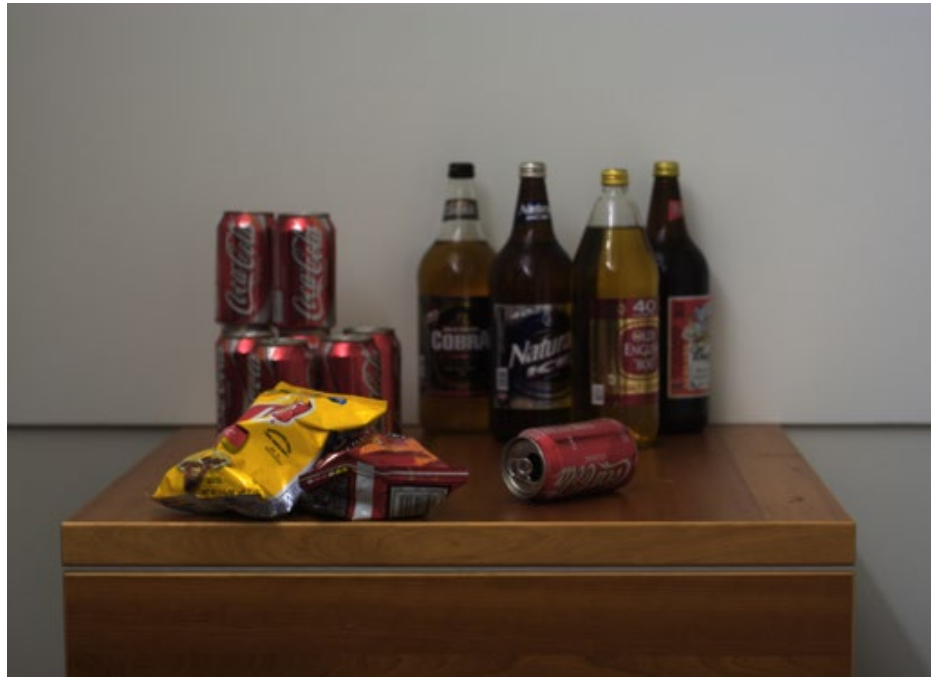
[Ng et al., SIGGRAPH 2005] [Lytro Inc.]

Measure 3D from a single 2D image

Coded aperture for single-image depth and refocusing



conventional vs
coded lens



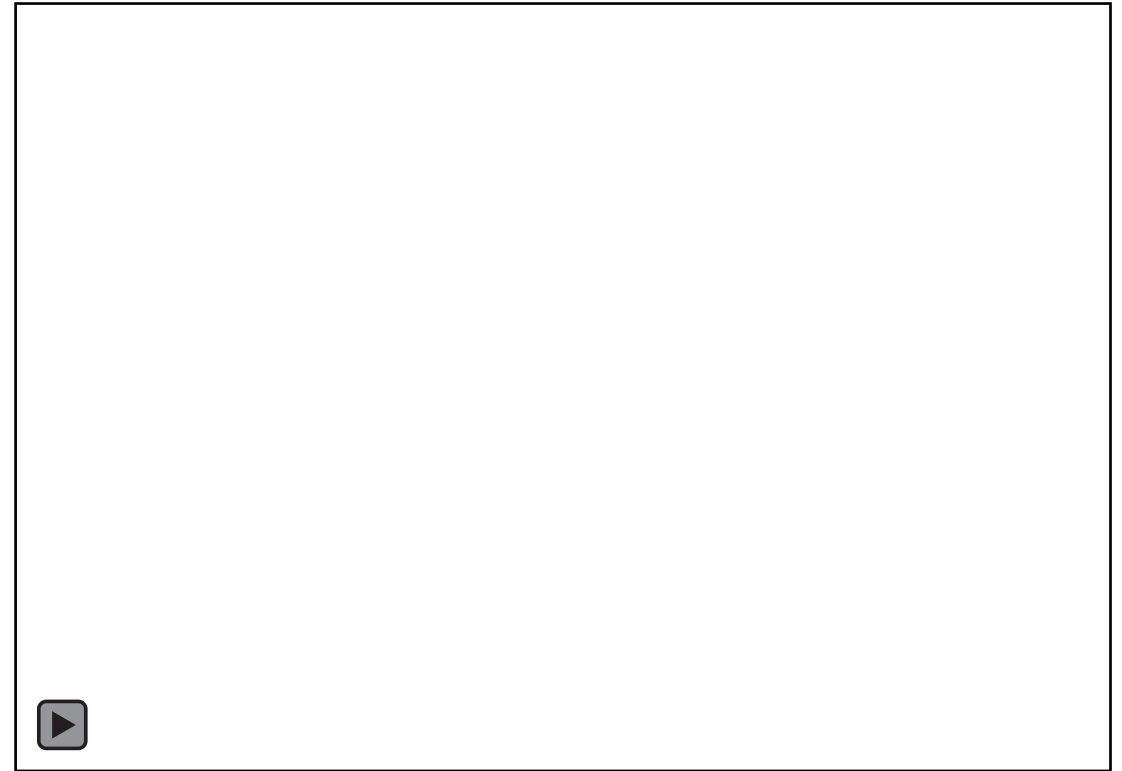
input image



inferred depth

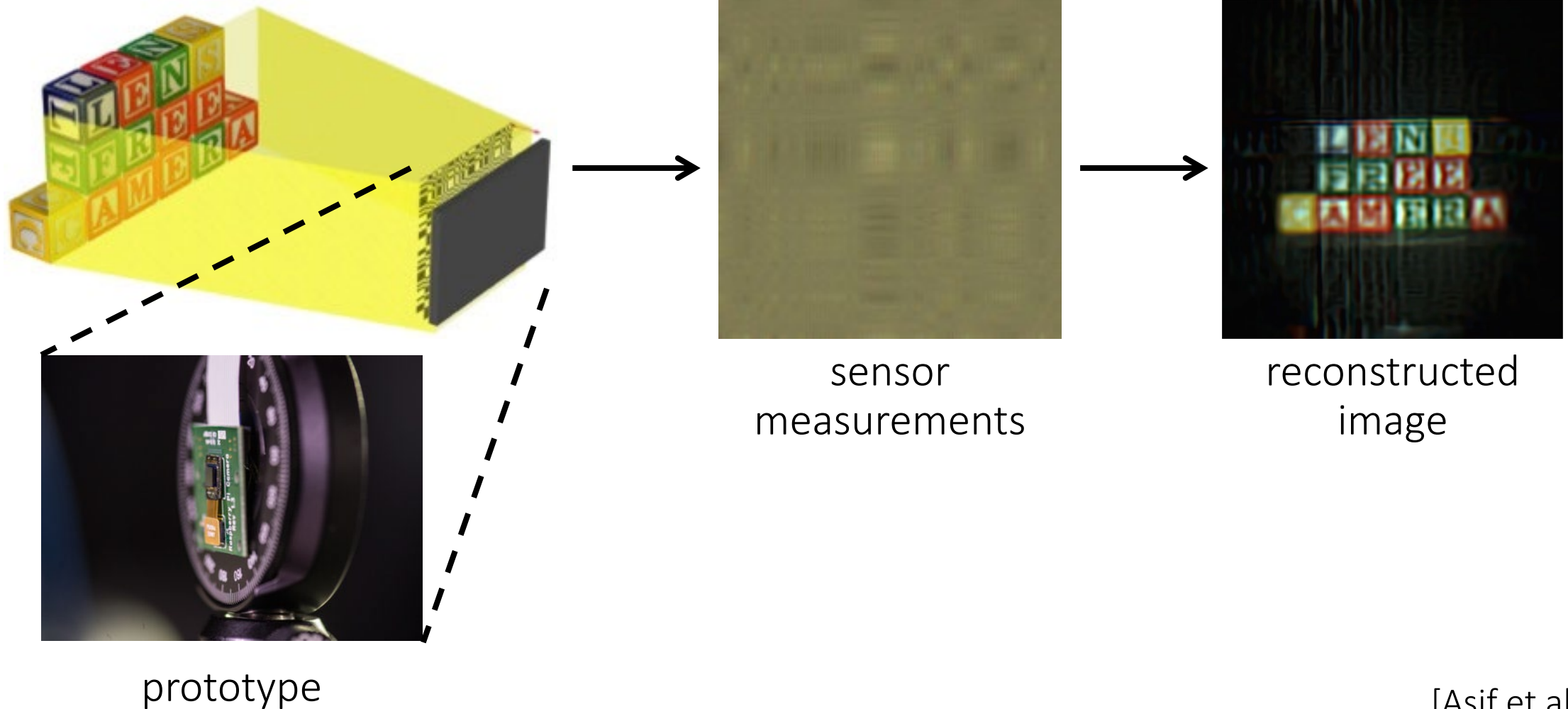
Measure 3D from a single 2D image

Coded aperture for single-image depth and refocusing



Remove lenses altogether

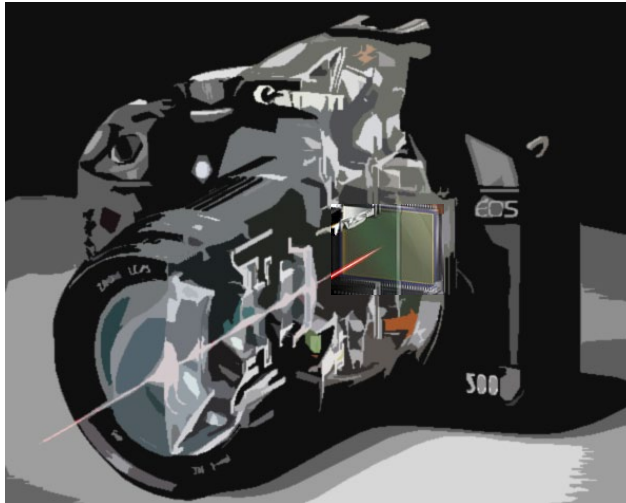
FlatCam: replacing lenses with masks



Computational photography



generalized optics
between scene and sensor



digital sensor to capture focused
light (electrical process)

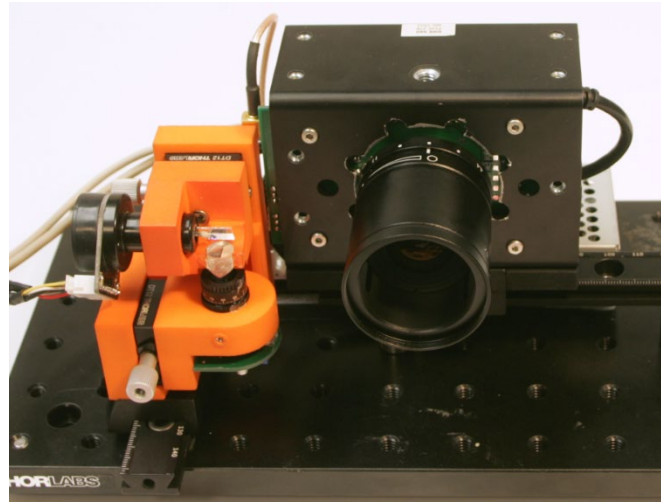


arbitrary computation
between sensor and image

Computational photography



generalized optics
between scene and sensor



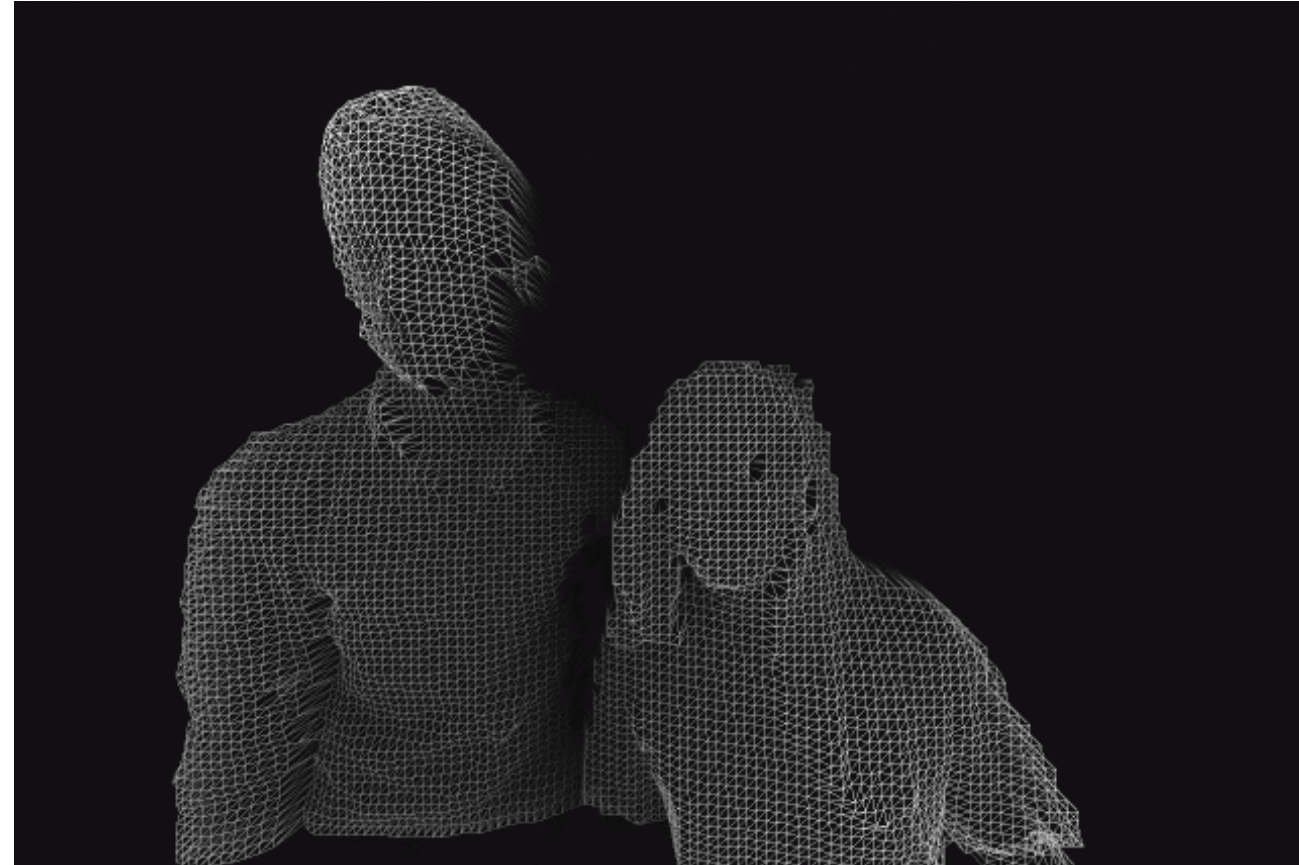
unconventional sensing
and illumination



arbitrary computation
between sensor and image

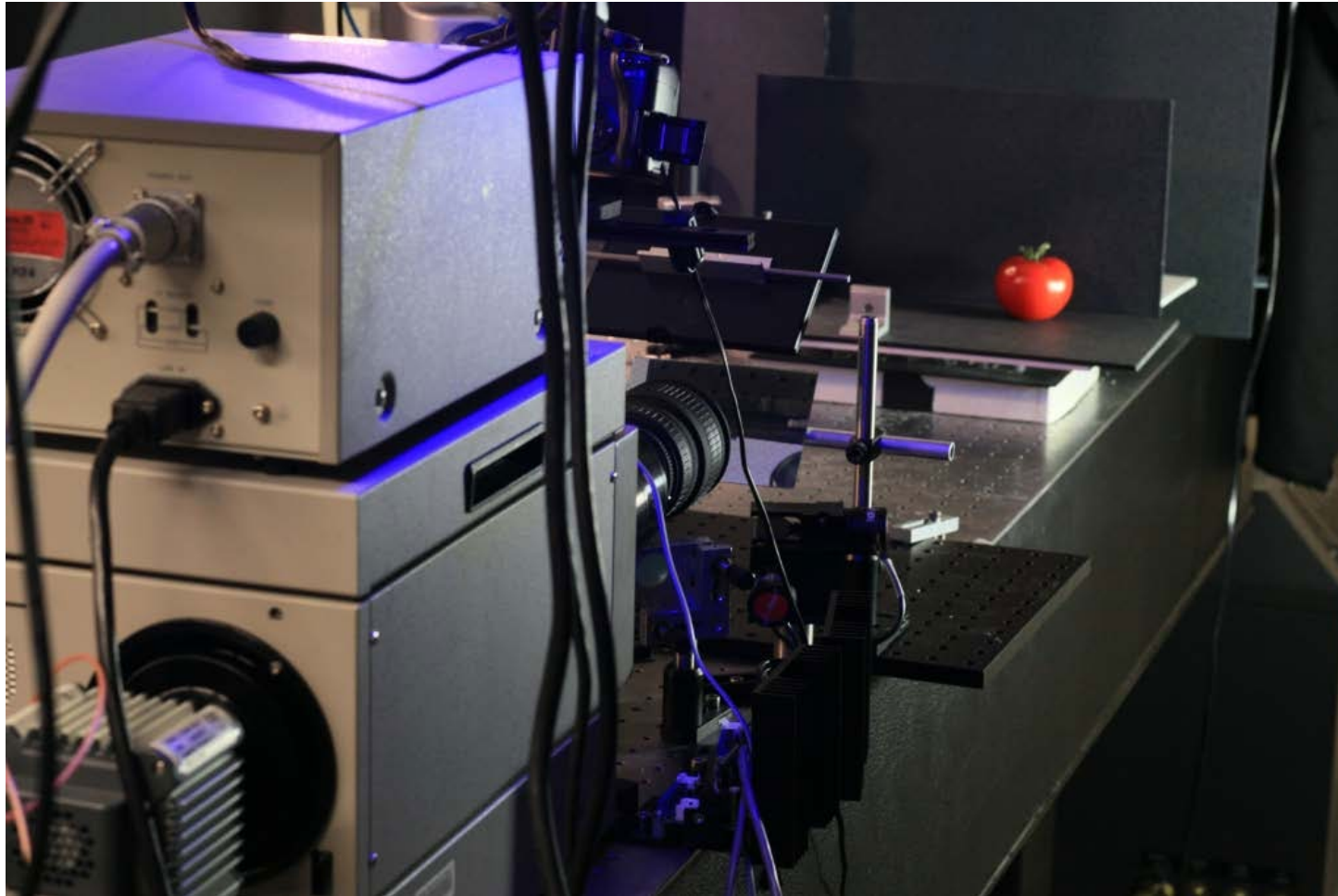
Measure depth

Time-of-flight sensors for real-time depth sensing



Measure light in flight

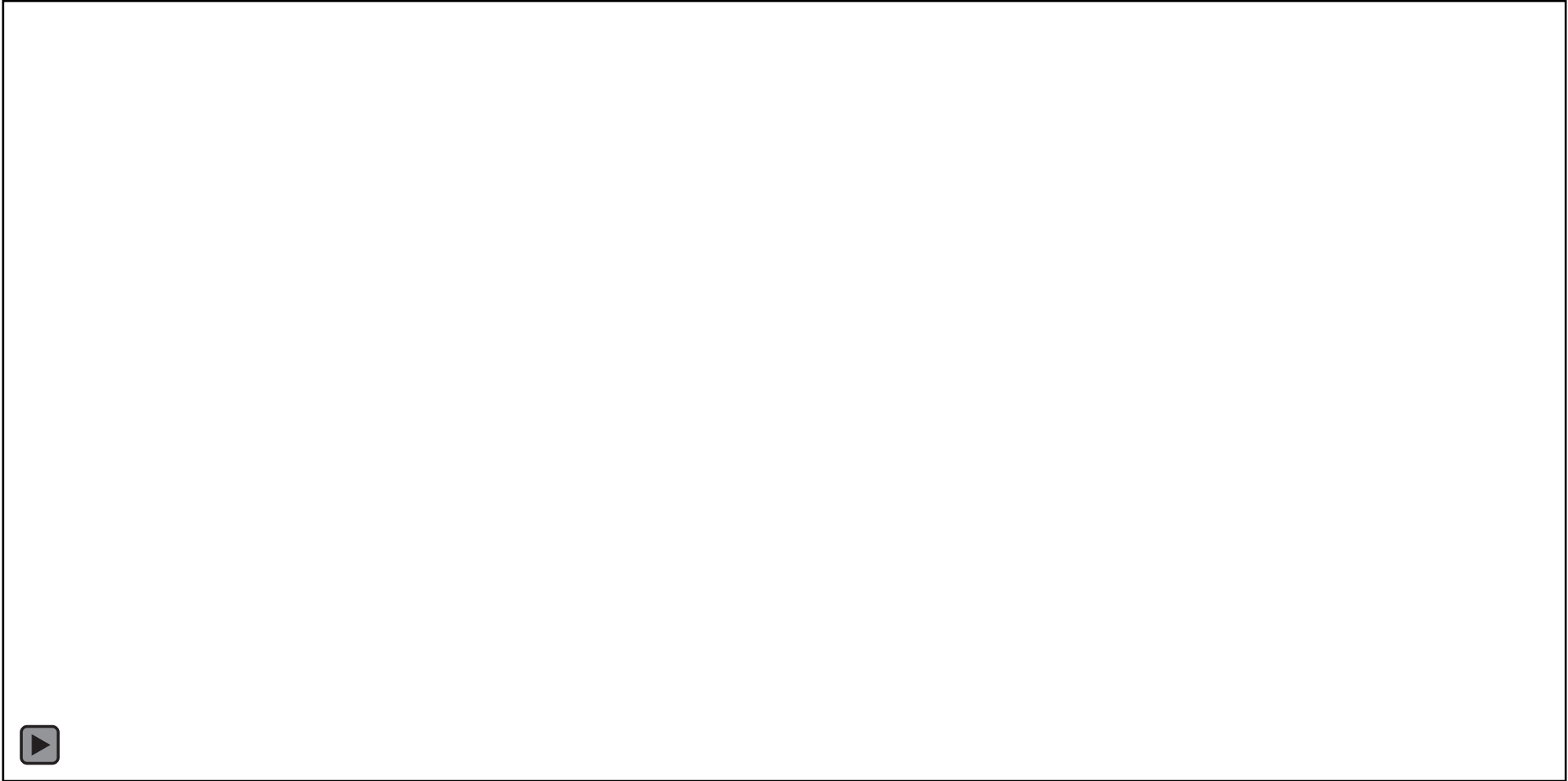
Streak camera for femtophotography



[Velten et al., SIGGRAPH 2013]

Measure light in flight

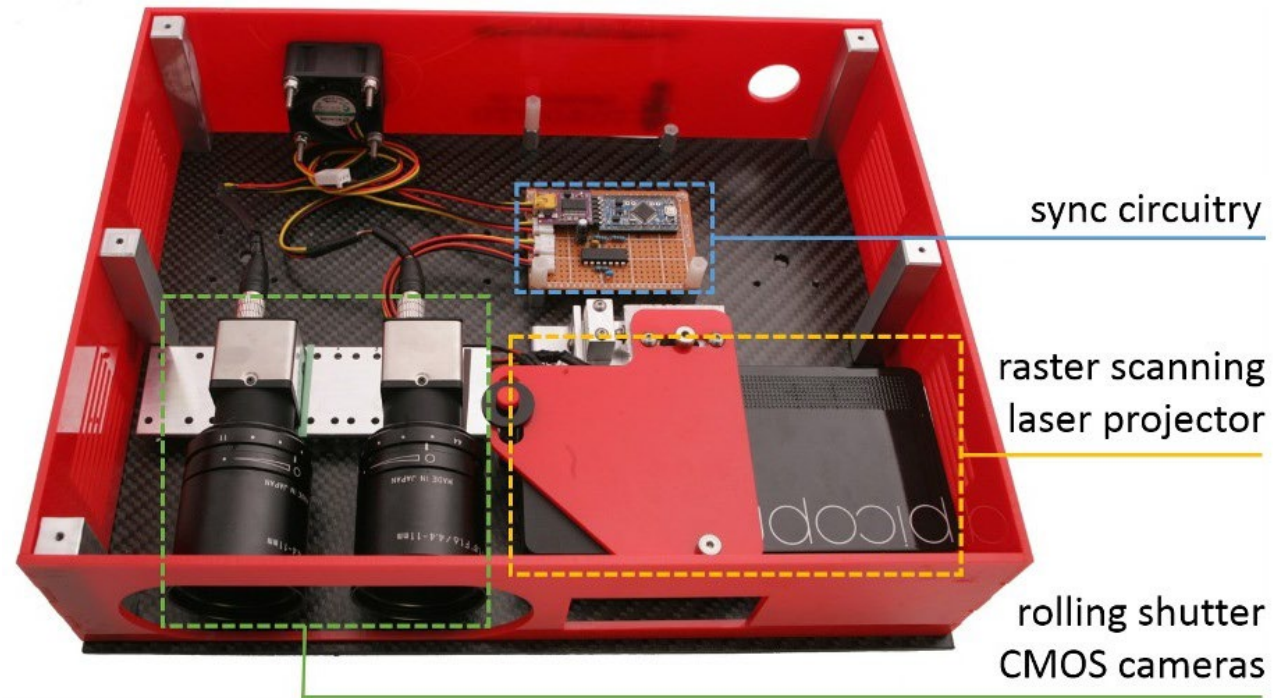
Streak camera for femtophotography



[Velten et al., SIGGRAPH 2013]

Measure photons selectively

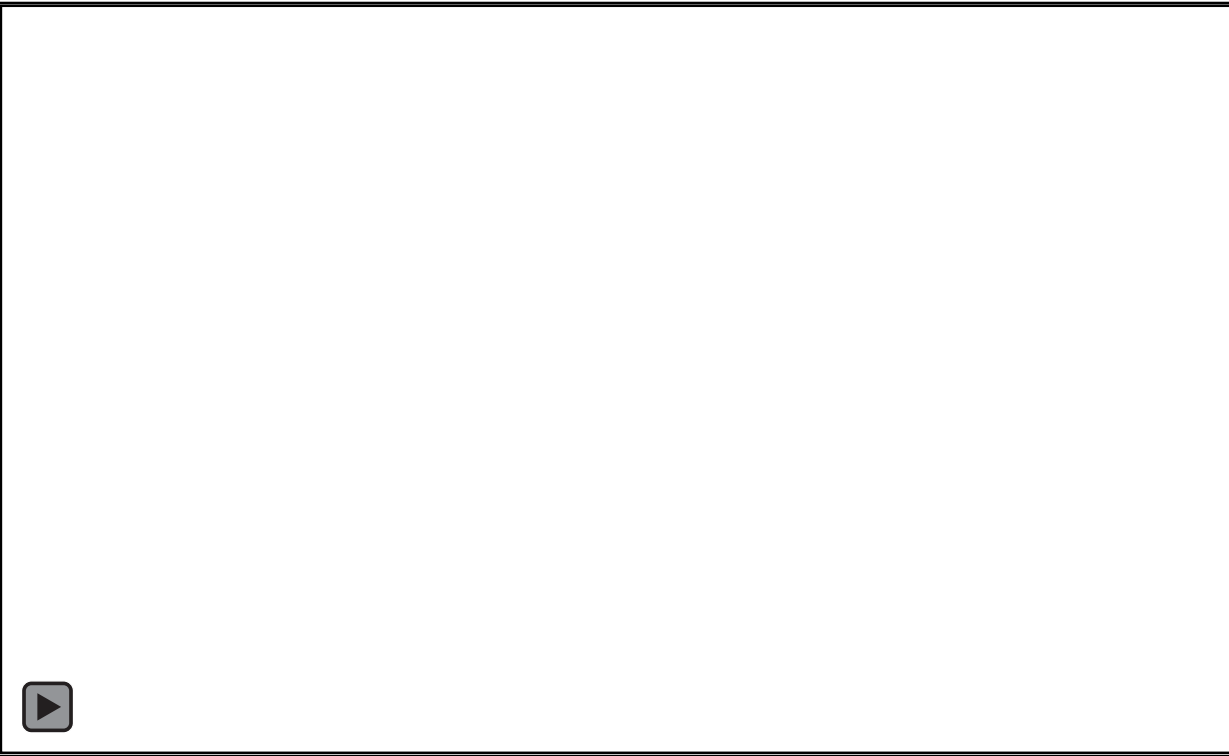
Structured light for epipolar imaging



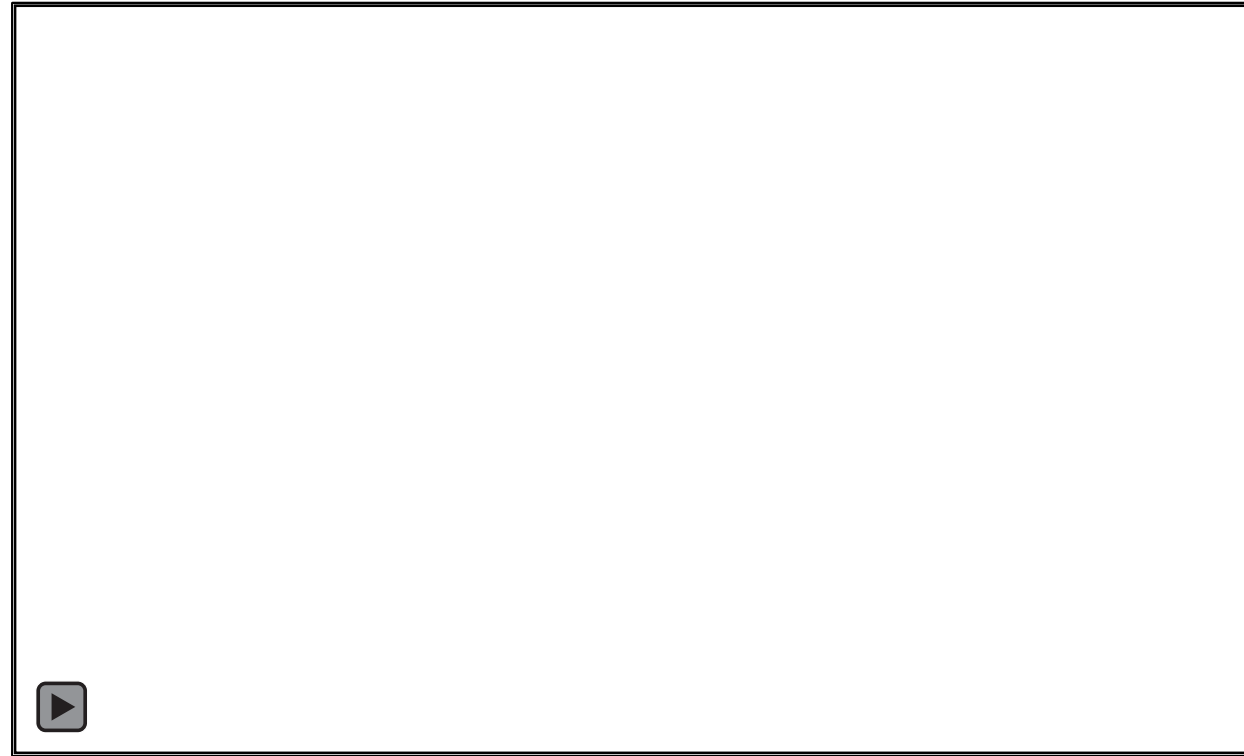
Measure photons selectively

One of your
homeworks!

Structured light for epipolar imaging



direct photons

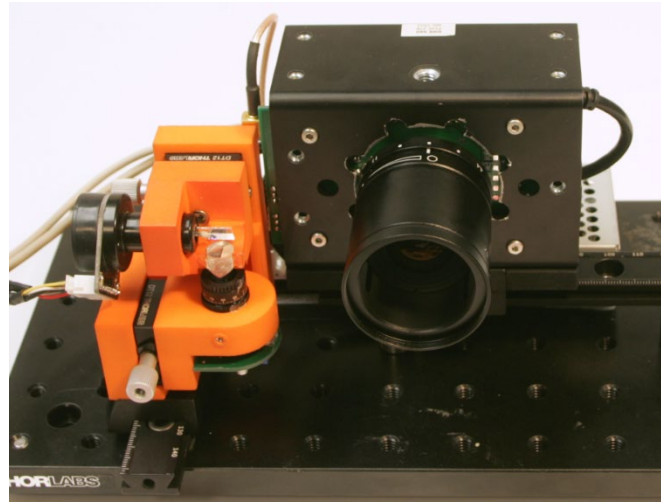


indirect photons

Computational photography



generalized optics
between scene and sensor



unconventional sensing
and illumination

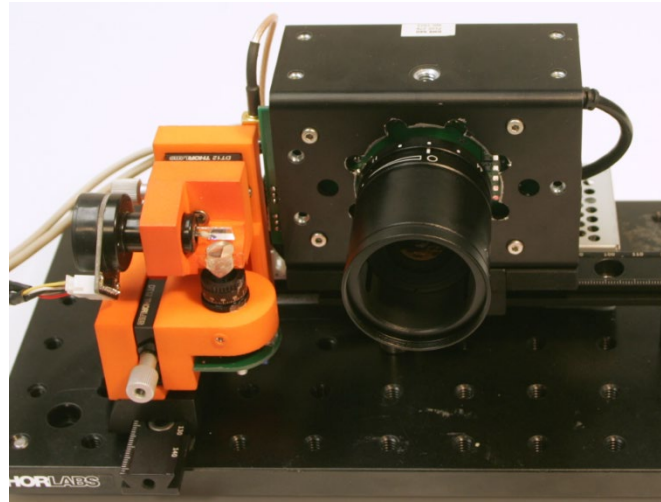


arbitrary computation
between sensor and image

Computational photography



generalized optics
between scene and sensor



unconventional sensing
and illumination

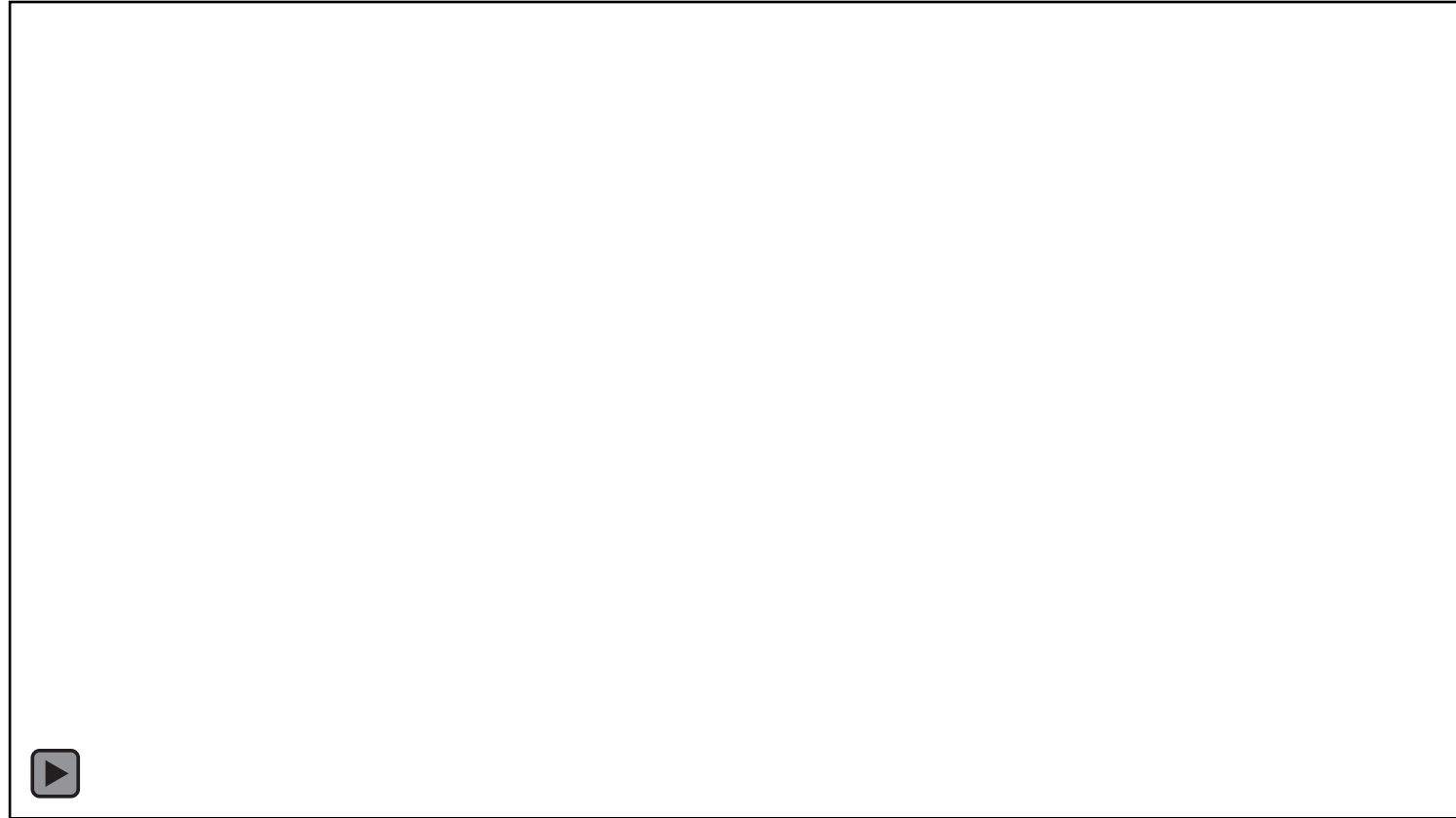
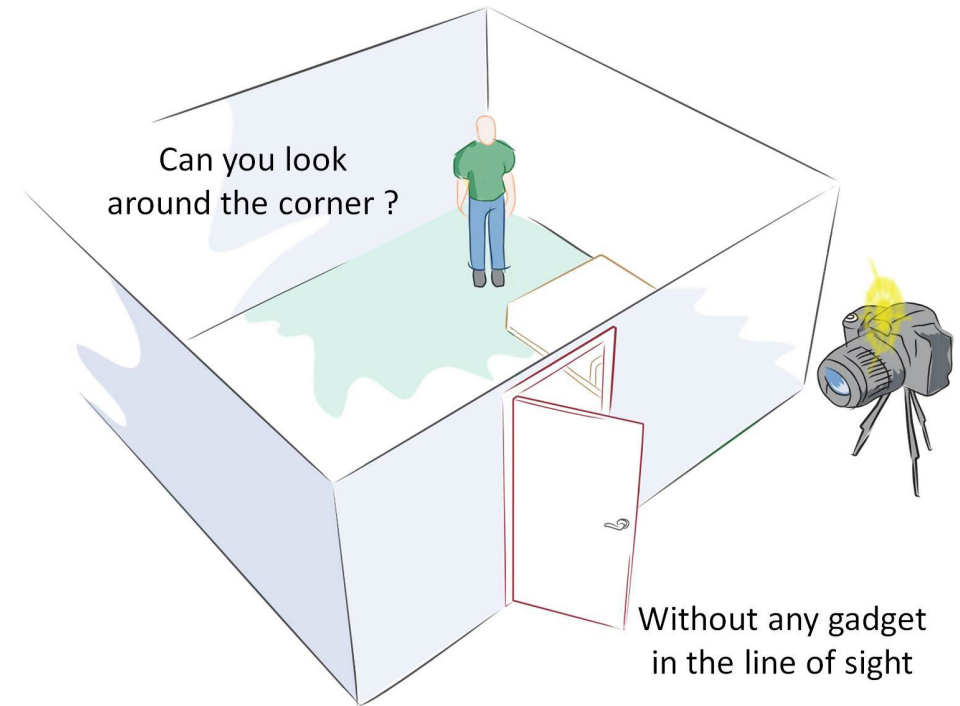


arbitrary computation
between sensor and image

joint design of optics, illumination, sensors, and computation

Putting it all together

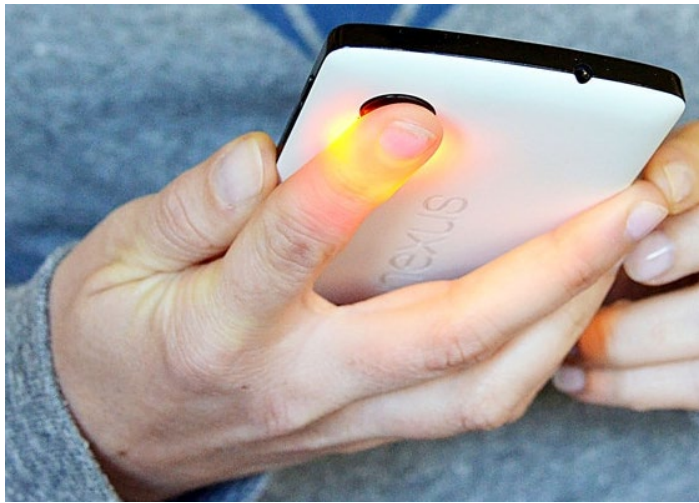
Looking around corners



Putting it all together

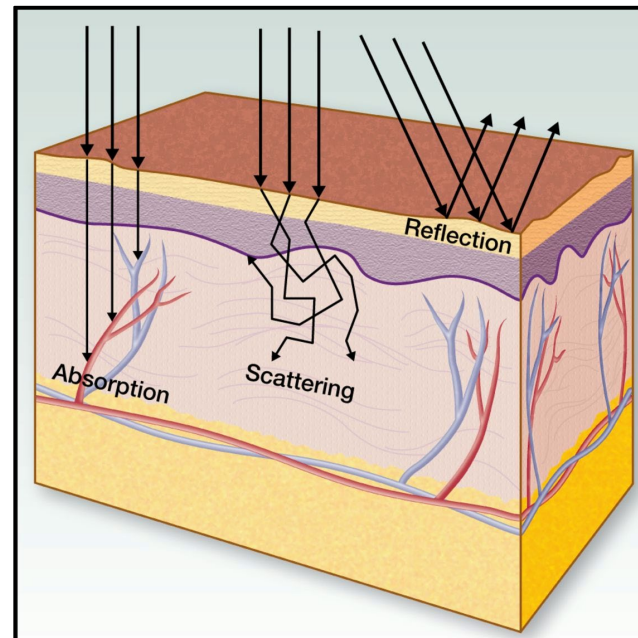
Looking through tissue

Opportunity



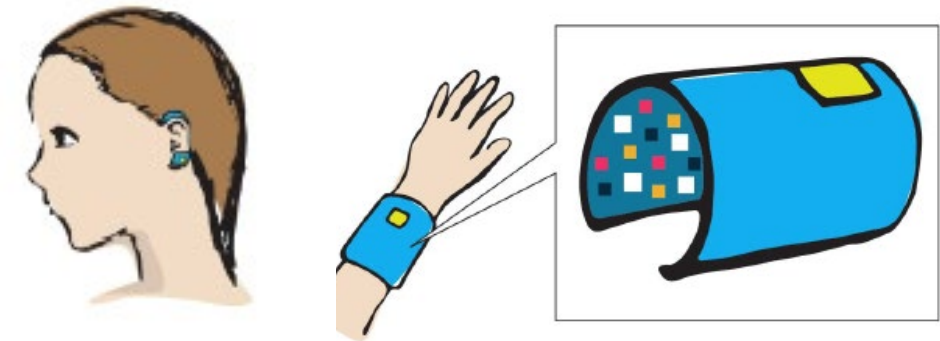
- + Light travels deep inside the body
- + It is non-ionizing (400-1100nm)
- + Cheap to produce and control

Scattering Barrier

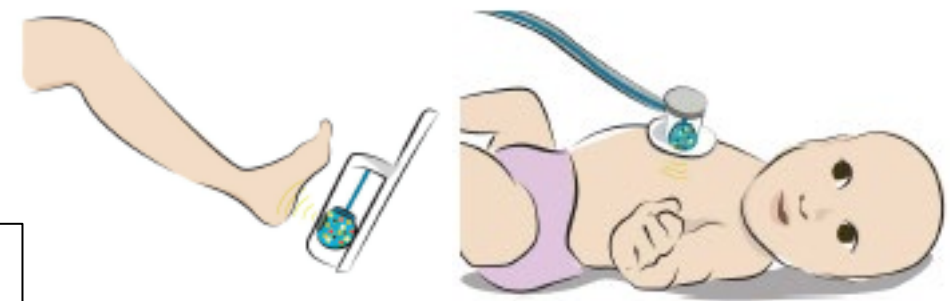


- Most pass-through photons are scattered
- Avg 10 scattering events per mm
- By 50mm, avg 500 scattering events !
- Large-scale inverse problem with low SNR

Practical imaging up to 50mm



Wearables (1-10mm)



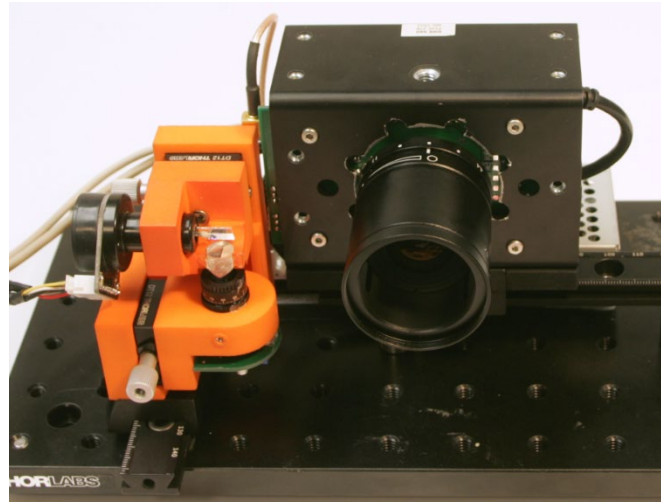
Non-invasive point of care devices (10-50mm)

[NSF Expedition]

Computational photography



generalized optics
between scene and sensor



unconventional sensing
and illumination



arbitrary computation
between sensor and image

joint design of optics, illumination, sensors, and computation

Course fast-forward and logistics

Course fast-forward

Tentative syllabus on the course website:

<https://graphics.cs.cmu.edu/courses/15-463>

- schedule and exact topics will most likely change during semester
- keep an eye out on the website for updates
- no required textbook, see suggestions on the website, and references at the end of lectures

Topics to be covered

Digital photography:

- optics and lenses
- color
- exposure
- aperture
- focus and depth of field
- image processing pipeline



[Photo from Gordon Wetzstein]

Topics to be covered

Image manipulation and fusion:

- high-dynamic-range imaging
- bilateral filtering
- edge-aware filtering
- gradient-domain image processing
- flash/no-flash photography
- high-performance image processing



Topics to be covered

Types of cameras:

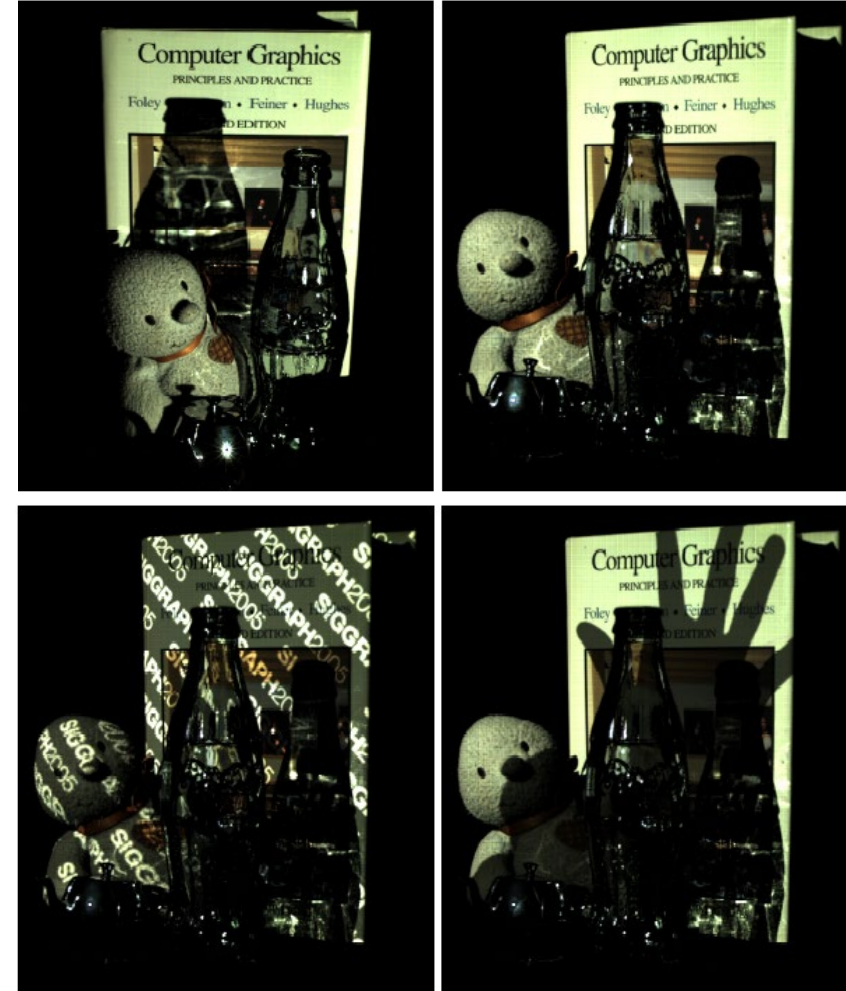
- geometric camera models
- lightfield cameras
- coded cameras
- lensless cameras
- compressive cameras
- hyperspectral cameras



Topics to be covered

Active illumination and sensing:

- time-of-flight sensors
- structured light
- computational light transport
- transient imaging
- non-line-of-sight imaging
- optical computing



Course online platforms

- Course website for all resources:

<https://graphics.cs.cmu.edu/courses/15-463>

- Canvas and Gradescope for homework submissions and grading.
- Slack for announcements and discussion.
- Links available on the course website.

Please take the start-of-semester survey!

- Posted on Slack as well:

https://docs.google.com/forms/d/e/1FAIpQLSceQ9UI9cyTSo3AvgpHxswr_pE_zMLGaWVoPsHqwr0diMm5ow/viewform

- We use the survey to:
 - Get a better idea of students' background.
 - Get a better idea of equipment needs.
 - Decide on day and time of office hours.

Prerequisites

At least one of the following:

- A computer vision course at the level of 16-385, 16-720, or 16-820.
- A computer graphics course at the level of 15-362, or 15-662.
- An image processing course at the level of 18-793.
- Specialized courses such as 15-468, 15-668, 15-868, or 18-453.

Pop quiz

How many of you know or have heard of the following terms:

- Gaussian and box filtering.
- Convolution and Fourier transform.
- Aliasing and anti-aliasing.
- Laplacian pyramid.
- Poisson blending.
- Homogeneous coordinates.
- Homography.
- RANSAC.
- Epipolar geometry.
- XYZ space.
- Multi-view stereo.
- Radiance and radiometry.
- Lambertian, diffuse, and specular reflectance.
- $n \cdot l$ lighting.
- Thin lens, prime lens, and zoom lens.
- Demosaicing.
- Refraction and diffraction.

Evaluation

- Six two-week homework assignments (80%):
 - Two parts, programming in **Python**, capturing your own photographs.
 - Generous extra credit components to help you catch up on missed credit.
 - Released and due every second Friday.
 - Five free late days, you can use them as you want. Penalty 10%/day after that.
 - No assignment may be submitted more than three days after deadline.
 - See course website for schedule and [submission guidelines](#).
 - **Strict submission deadlines. No extra late days except for medical reasons.**
- Final project (20%):
 - See [final project page](#) on course website for detailed logistics (updated this year).
 - Start thinking about final project early, especially if you require imaging equipment.
 - **No exam or final presentations. Final project videos will appear on YouTube.**

Do I need a camera?

- You will need to take your own photographs for assignments 1-6 (all of them):
 - Assignment 1: pinhole camera – you need a high-sensitivity camera.
 - Assignment 2: HDR – you need a camera with manual exposure controls.
 - Assignment 3: image filtering – you can use your phone camera if it has flash.
 - Assignment 4: lightfields – you need a camera with manual focus control.
 - Assignment 5: photometric stereo – you need a camera with RAW support.
 - Assignment 6: structured light – you can use your phone camera.
- We have 60 Nikon D3X00 kits (camera + lens + tripod) for students.
 - If you have your own camera, please use that!
 - [Tutorial](#) available on course website.
- Sign up for a camera (distributed in the second week of classes):
<https://docs.google.com/spreadsheets/d/1Ac8DcA3ucA8nQGsjKJ-JOvcAzXv4nLKnzuqzADZ0Rpw/>



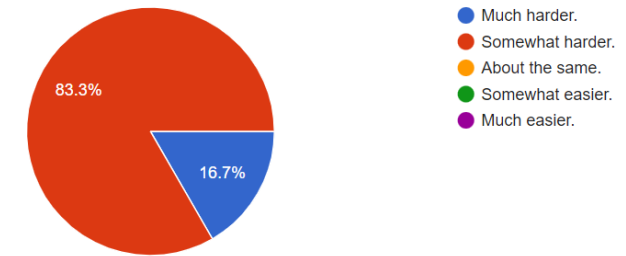
Tips

- Capturing your own photos is *very* time consuming and tedious. Lots of handiwork and trial and error.
- Do not spend all your late days on assignment 1. Assignments 2, 5, 6 take up a *lot* more time.
- Plan how to use late days to accommodate CVPR or other paper deadlines, job interviews, friends' weddings, other coursework, research, etc.
- Start early! Do at least a cursory read of each homework assignment the day it is released, and plan programming and data capture components.
- Uploading solutions with many images can be slow. Plan to submit early to avoid wasting late days.

On average, how did the homework assignments in this course compare to homework assignments in other courses you have taken in terms of difficulty?

[Copy](#)

6 responses



Explain your previous answer.

3 responses

In the parts where we needed to capture our own data, there were more practical aspects to consider such as finding the right materials or finding a dark room. It can be very time-consuming since they required trial-and-error.

Definitely takes more time than assignments in the other course as we have both theoretical and hands-on task for each assignment. There are some challenges to generate my own data set (e.g., at the first place I did not know whether my light condition is enough, and afterward I realize that I need more light, so I took pictures again etc). However, the assignment instructions are clear so it is easy to follow step by step.

I think for me, a lot of the math was already hard to fully understand. As an undergrad, we typically don't read research papers in our classes, so that was also new to me. The research papers often detailed harder math and theory than was discussed in class, which made it difficult to figure out what to do. Most of the homework assignments also took a lot of trial and error to get the code completely right, and I often found it near impossible to debug if I had a minor conceptual understanding, since my code would "look" correct to me, and the visual outputs would usually not provide any clue as to where the bug might be. There was also a lot of documentation reading and figuring out what was possible with numpy / how to actually do tasks properly using it. I think this more systems-related aspect combined with the need to really understand the math/theory behind the assignments made the assignments harder than other class assignments, which would often either focus on systems-related challenges or theory/algorithm-related

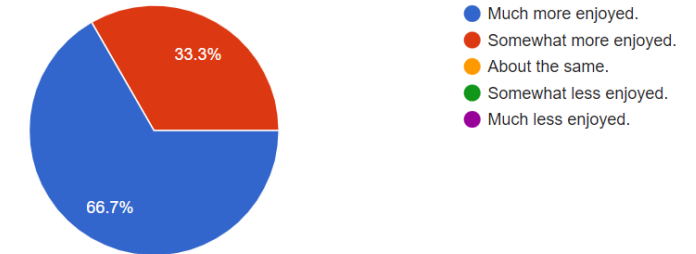
Tips

- Capturing your own photos is *very* time consuming and tedious. Lots of handiwork and trial and error.
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- Start early! Do at least a cursory read of each homework assignment the day it is released, and plan programming and data capture components.
- Uploading solutions with many images can be slow. Plan to submit early to avoid wasting late days.

On average, how did the homework assignments in this course compare to homework assignments in other courses you have taken in terms of how much you enjoyed them?

[Copy](#)

6 responses



What are the strongest features of this course?

6 responses

Homeworks, lectures

Homework assignments that really forced the students to know how to implement the core ideas in class.

Getting to do advanced image processing on images we took ourselves is so amazing

Very interesting

both theoretical contents and hands-on implementation

The rewarding/interactive/photography homeworks, and the lectures

Don't make the homeworks easier!

Final project competition

- At the end of the semester, we will ask other computational photography faculty at CMU (Srinivasa Narasimhan, Matthew O'Toole, Aswin Sankaranarayanan, Jun-Yan Zhu) to watch final project videos and vote on the two best final projects.
- The two winning students will receive a **free DSLR camera kit** (same as the one provided for homework).
- Previous years' projects: [Fall 2020](#), [Fall 2021](#), [Fall 2022](#), [Fall 2023](#), [Fall 2024](#), [Fall 2025](#).



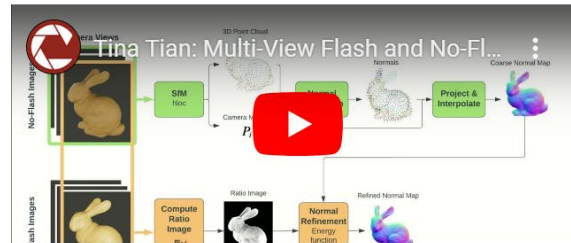
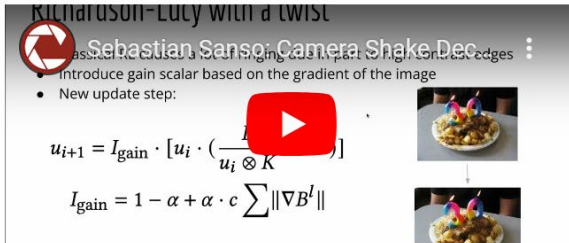
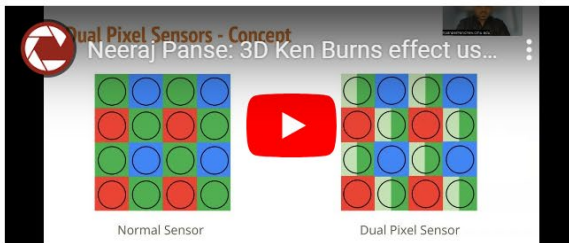
Final project competition

15-463, 15-663, 15-862 Computational photography

Carnegie Mellon University, Fall 2023

Final project competition

🏆 Winners (alphabetical order)



15-463 Computational Photography, Fall 2023

Carnegie Mellon Computational Imaging

Public

26 videos 881 views Last updated on Dec 19, 2023

Final projects from the Fall 2023 offering of 15-463, 15-663, 15-862 Computational Photography at Carnegie Mellon University.

Course website:
http://graphics.cs.cmu.edu/courses/15-463/2023_fall/

Sort

Aman Mehra: Exploring Priors for Inverse Rendering
 Carnegie Mellon Computational Imaging • 399 views • 8 months ago

Andrew Zhao: Faster, More Practical, and Higher Quality Unstructured Light Field Photography
 Carnegie Mellon Computational Imaging • 76 views • 8 months ago

Eileen Li: Single-View Computational Zoom with Multi-Plane Images
 Carnegie Mellon Computational Imaging • 66 views • 8 months ago

Gavin Zhu: Image Stylization by Edge-Aware Processing
 Carnegie Mellon Computational Imaging • 54 views • 8 months ago

Haejoon Lee: Illumination Source Separation using a Flash Photography Technique...
 Carnegie Mellon Computational Imaging • 60 views • 8 months ago

Hanyu Chen: Adaptive LiDAR Sampling Based on Generalized Winding Numbers
 Carnegie Mellon Computational Imaging • 57 views • 8 months ago

Isa Lie: Dual Photography
 Carnegie Mellon Computational Imaging • 53 views • 8 months ago

Jingguo Liang: Coded Aperture
 Carnegie Mellon Computational Imaging • 71 views • 8 months ago

All final project videos will be available on course website and YouTube:

<https://www.youtube.com/@cmu-computational-imaging>

Contact information and office hours

- Feel free to email us about administrative questions.
 - Please use [15463] in email title!
- Ask technical questions on Slack.
 - We won't answer technical questions through email.
- We will decide office hours using votes in the start-of-semester survey.
 - Office hours will be in person in Smith Hall (EDSH) Rm 236 (graphics lounge).
 - Feel free to email Yannis about additional office hours.
 - You can also just drop by Yannis' office (Smith Hall (EDSH) Rm 225).
 - You can also post on Slack for additional office hours.
 - Office hours for this week only: **Wednesday, 1–2 pm ET.**

Interested in research?

- Check out the Carnegie Mellon computational imaging group:

Website: <https://imaging.cs.cmu.edu/>

YouTube: <https://www.youtube.com/@cmu-computational-imaging>

- Email Yannis if you want to be added to the imaging group mailing list and attend our weekly meetings (day and time for the semester TBD).
- We are actively recruiting research assistants for projects relating to imaging, rendering, and graphics in general. Please email Yannis if interested.

Carnegie Mellon computational imaging group

IMAGING @ CMU TEAM PUBLICATIONS COURSES

Publications

 **Walk on Stars: A Grid-Free Monte Carlo Method for PDEs with Neumann Boundary Conditions**
Rohan Sawhney*, Bailey Miller*, Ioannis Gkioulekas†, Keenan Crane†. *ACM Transactions on Graphics (SIGGRAPH) 2023*.

 **Boundary Value Caching for Walk on Spheres**
Bailey Miller*, Rohan Sawhney*, Keenan Crane†, Ioannis Gkioulekas†. *ACM Transactions on Graphics (SIGGRAPH) 2023*.

 **Split-Lohmann Multifocal Displays**
Yingsi Qin, Wei-Yu Chen, Matthew O'Toole, Aswin C. Sankaranarayanan. *ACM Transactions on Graphics (SIGGRAPH) 2023*.

 **Analyzing Physical Impacts using Transient Surface Wave Imaging**
Tianyuan Zhang, Mark Sheinin, Dorian Chan, Mark Rau, Matthew O'Toole, Srinivas G Narasimhan. *CVPR 2023*.

 **Megahertz Light Steering without Moving Parts**
Adithya Pediredla, Srinivasa G. Narasimhan, Maysamreza Chamanzar, Ioannis Gkioulekas. *CVPR 2023*.

 **Passive Micron-scale Time-of-Flight with Sunlight Interferometry**
Alankar Kotwal, Anat Levin, and Ioannis Gkioulekas. *CVPR 2023*.

 **Swept-Angle Synthetic Wavelength Interferometry**

IMAGING @ CMU TEAM PUBLICATIONS COURSES

Courses

 **15-468, 15-668, 15-868 Physics-based Rendering**
Ioannis Gkioulekas. *Carnegie Mellon University (spring semesters)*.

 **15-463, 15-663, 15-862 Computational Photography**
Ioannis Gkioulekas. *Carnegie Mellon University (fall semesters)*.

 **Computational Interferometric Imaging**
Alankar Kotwal, Florian Willomitzer, Ioannis Gkioulekas. *SIGGRAPH 2023 course*.

 **Physics-Based Rendering and Its Applications in Computational Photography and Imaging**
Adithya Pediredla, Ioannis Gkioulekas. *CVPR 2023 tutorial*.

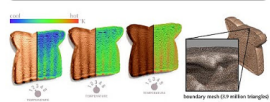
 **Physics-Based Differentiable Rendering**
Shuang Zhao, Ioannis Gkioulekas. *CVPR 2021 tutorial*.

 **Computational Cameras and Displays**
Matthew O'Toole, Gordon Wetzstein. *SIGGRAPH 2014 course*.

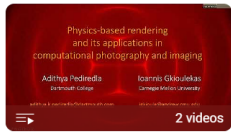
 **Carnegie Mellon Computational Imaging**
@cmu-computational-imaging 59 subscribers 43 videos
YouTube channel for the computational imaging group at Carnegie Mellon ... >
imaging.cs.cmu.edu and 5 more links

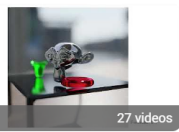
HOME VIDEOS PLAYLISTS COMMUNITY CHANNELS ABOUT

Research

 **Project highlights**
Carnegie Mellon Computational Imaging
Walk on Stars: A Grid-Free Monte Carlo Method for PDEs with Neumann Boundary Conditions • 33:04
Split-Lohmann Multifocal Displays [SIGGRAPH 2023] • 5:33
VIEW FULL PLAYLIST

Teaching

 **Physics-based rendering and its applications in computational photography and imaging**
Adithya Pediredla, Ioannis Gkioulekas
2 videos
VIEW FULL PLAYLIST

 **15-463 Computational Photography, Fall 2022**
Carnegie Mellon Computational Imaging
VIEW FULL PLAYLIST

Resources on both research and teaching (CVPR tutorials, SIGGRAPH courses)

International Conference on Computational Photography YouTube channel

<https://www.youtube.com/@iccp-conference>

ICCP
236 subscribers

HOME VIDEOS PLAYLISTS CHANNELS ABOUT

ICCP'22: Monday 8/1 Sessions ▶ PLAY ALL

8/1 Monday Morning Session
ICCP
1.7K views • Streamed 1 day ago

8/1 Monday Afternoon Session
ICCP
1.8K views • Streamed 1 day ago

ICCP'22: Tuesday 8/2 Sessions ▶ PLAY ALL

8/2 Tuesday Morning Session
ICCP
3.2K views • Streamed 17 hours ago

8/2 Tuesday Afternoon Session
ICCP
2.1K views • Streamed 14 hours ago

ICCP'22: Wednesday 8/3 Sessions ▶ PLAY ALL

8/3 Wednesday Morning Session
ICCP
1 waiting • Scheduled for 8/3/22, 8:45 AM
NOTIFY ME

8/3 Wednesday Afternoon Session
ICCP
Scheduled for 8/3/22, 1:45 PM
NOTIFY ME

ICCP'22: Posters and Demos ▶ PLAY ALL

Poster 1. D-Flat: A Differentiable Flat-Optics...
ICCP
155 views • 4 days ago

Poster 2. Single-Photon Structured Light
ICCP
103 views • 4 days ago

Poster 3. Super 3D vision enabled by bionic...
ICCP
204 views • 4 days ago

Poster 10. Neural Nano-Optics for High-quality Thin...
ICCP
65 views • 4 days ago

Poster 11. Holocurtains: Programming Light Curtain...
ICCP
25 views • 4 days ago

Poster 13. Swept-angle Synthetic Wavelength...
ICCP
64 views • 4 days ago

ICCP'21

ICCP'21: Sunday May 23rd Sessions
ICCP
Updated 4 days ago
VIEW FULL PLAYLIST

ICCP'21: Monday May 24th Sessions
ICCP
Updated 4 days ago
VIEW FULL PLAYLIST

ICCP'21: Tuesday May 25th Sessions
ICCP
Updated 4 days ago
VIEW FULL PLAYLIST

ICCP'21: Posters and Demos
ICCP
Updated 4 days ago
VIEW FULL PLAYLIST

ICCP'21: Gather.Town
ICCP
Updated 4 days ago
VIEW FULL PLAYLIST

ICCP'20

ICCP 2020 - Day 1
ICCP 2020
VIEW FULL PLAYLIST

ICCP 2020 - Day 2
ICCP 2020
VIEW FULL PLAYLIST

ICCP 2020 - Day 3
ICCP 2020
VIEW FULL PLAYLIST

ICCP 2020 - Posters/Demos
ICCP 2020
VIEW FULL PLAYLIST

ICCP'19

ICCP 2019
ICCP
ICCP2019 Oral 01: Thermal Non-Line of Sight Imaging • 22:44
ICCP2019 Oral 09: PhaseCam3D – Learning Phase Masks for Passive Single View Depth Estimation • 20:15
VIEW FULL PLAYLIST

ICCP'18

ICCP 2018
ICCP • Updated 3 days ago
ICCP 2018 Talks: Session 1 • 1:11:46
ICCP 2018 Talks: Session 2 • 1:08:39
VIEW FULL PLAYLIST

ICCP'11

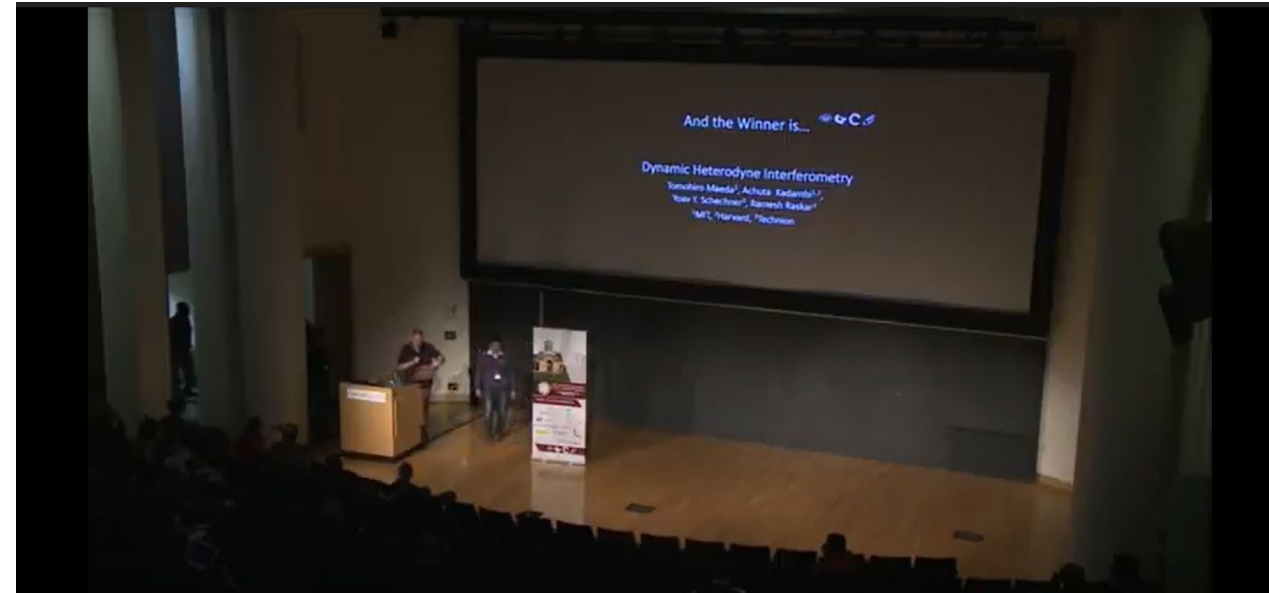
ICCP11 International Conference on Computational Photography
CMU Robotics Institute
Kari Pulli: FCam - An architecture and API for computational cameras • 47:26
Markus Testorf: Phase-Space Tools for Computational Imaging and Photography • 1:19:45
VIEW FULL PLAYLIST

CMU has a strong presence at ICCP



ICCP 2011

ICCP 2018



Please take the start-of-semester survey and sign up for a camera before the next lecture!

Survey link:

https://docs.google.com/forms/d/e/1FAIpQLSceQ9UI9cyTSo3AvgpHxswr_pE_zMLGaWVoPsHqwr0diMm5ow/viewform

Camera sign up:

<https://docs.google.com/spreadsheets/d/1Ac8DcA3ucA8nQGsjKJ-JOvcAzXv4nLKnzuqzADZ0Rpw/>

Both links available on Slack.